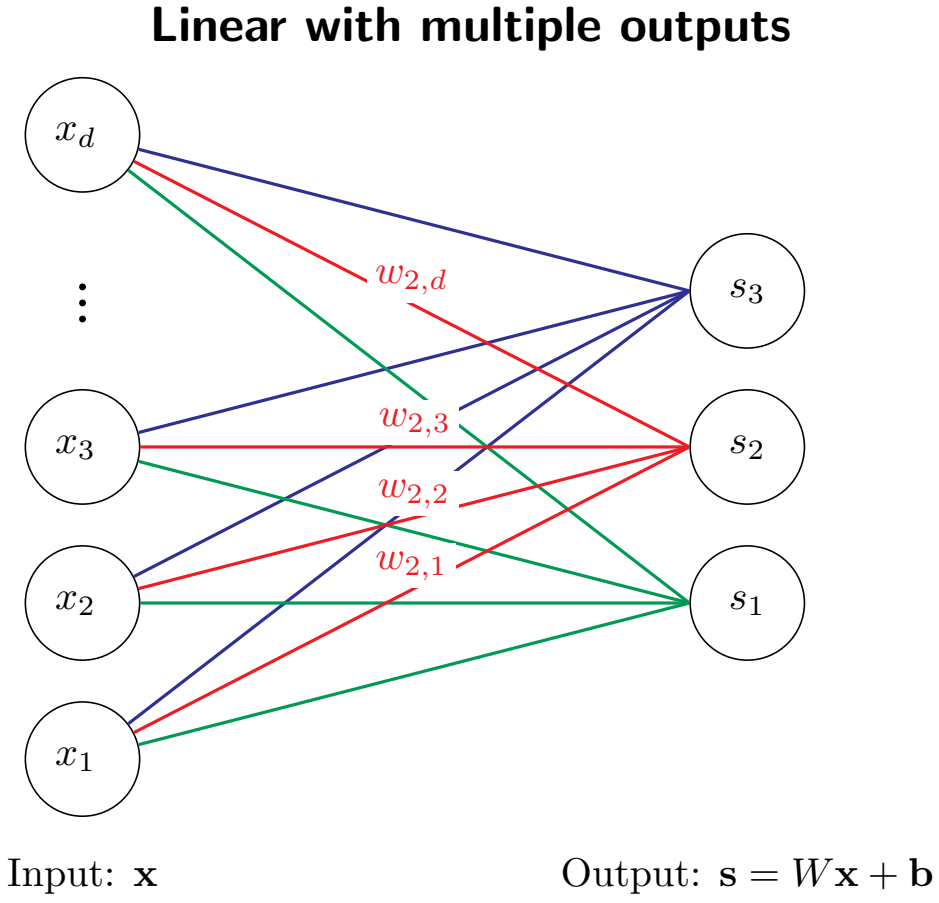
Gradient computations

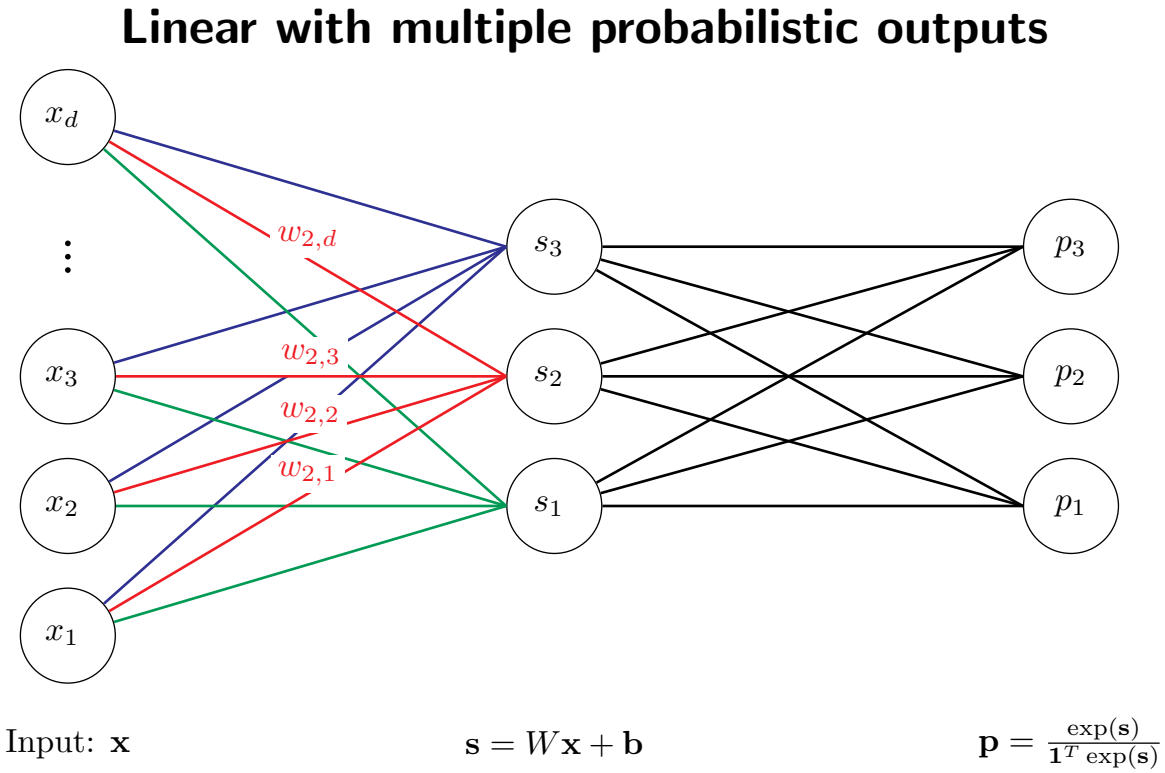
Computation Graphs and the Back-propagation algorithm

Visualization of our multi-class classification function



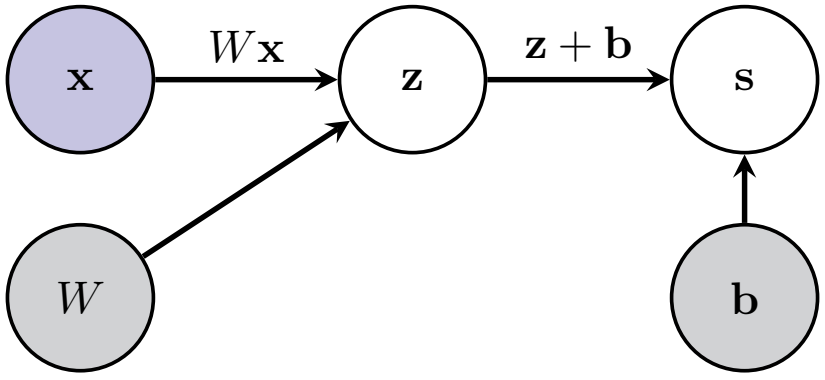
Final decision: $g(\mathbf{x}) = \arg\max_j s_j$

Visualization of our multi-class classification function



Final decision: $g(\mathbf{x}) = \arg\max_j p_j$

Computational graph of the multiple linear function



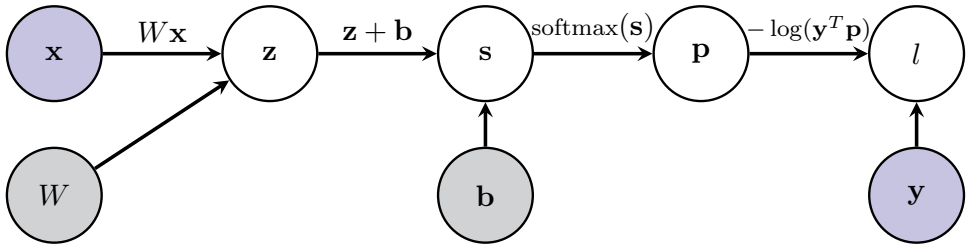
The computational graph:

- Represents order of computations.
- Displays the dependencies between the computed quantities.
- User input, parameters that have to be learnt.

Computational Graph helps automate gradient computations.

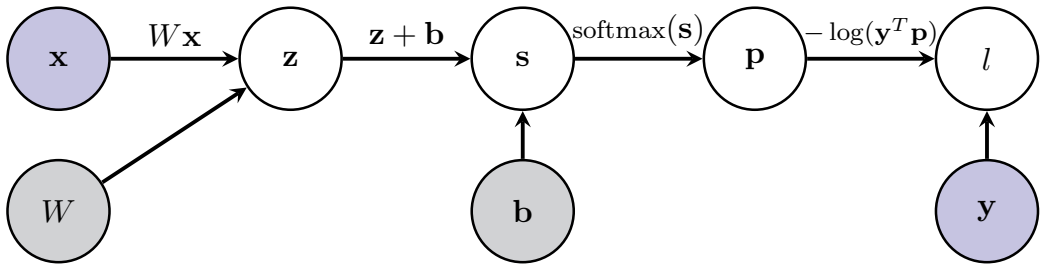
Computational graph of the complete loss function

- Linear scoring function + SOFTMAX + cross-entropy loss



where $\mathbf{y}$ is the 1-hot response vector induced by the label y.

To learn $W, \mathbf{b}$ need to compute gradients



- Let l be the loss function defined by the computational graph.
- Find $W, \mathbf{b}$ by optimizing

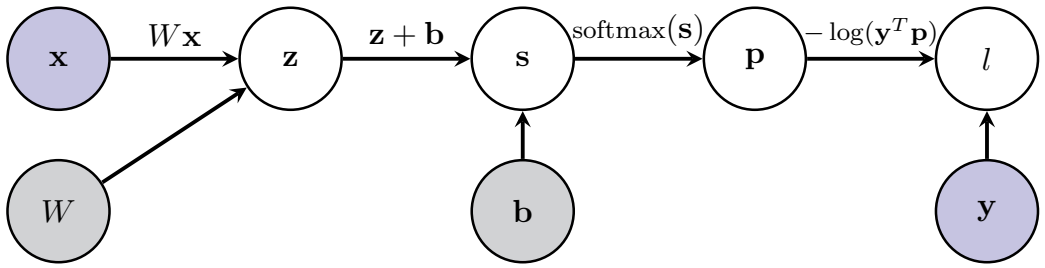
$$\arg\max_{W,\mathbf{b}} \frac{1}{|\mathcal{D}|} \sum_{(\mathbf{x},y)\in\mathcal{D}} l(\mathbf{x}, y, W, \mathbf{b})$$

- Solve using a variant of **mini-batch gradient descent**

  $\Longrightarrow$ need to efficiently compute the gradient vectors

$$\nabla_W l(\mathbf{x}, y, W, \mathbf{b})|_{(\mathbf{x},y)\in\mathcal{D}} \quad \text{and} \quad \nabla_{\mathbf{b}} l(\mathbf{x}, y, W, \mathbf{b})|_{(\mathbf{x},y)\in\mathcal{D}}$$

How do we compute these gradients?



- Let l be the complete loss function defined by the computational graph.
- How do we efficiently compute the gradient vectors

$$\nabla_W l(\mathbf{x}, y, W, \mathbf{b})|_{(\mathbf{x},y)\in\mathcal{D}} \quad \text{and} \quad \nabla_{\mathbf{b}} l(\mathbf{x}, y, W, \mathbf{b})|_{(\mathbf{x},y)\in\mathcal{D}}?$$

- Answer: Back Propagation
- BackProp relies on the **chain rule** applied to the **composition of functions**.
- Example: the composition of functions

$$l(\mathbf{x}, y, W, \mathbf{b}) = -\log(\mathbf{y}^T \mathrm{softmax}(W\mathbf{x}+\mathbf{b}))$$

Chain Rule for functions with a scalar input and a scalar output

Differentiation of the composition of functions

- Have two functions $g : \mathbb{R} \to \mathbb{R}$ and $f : \mathbb{R} \to \mathbb{R}$.
- Define $h : \mathbb{R} \to \mathbb{R}$ as the composition of f and g:

$$h(x) = (f \circ g)(x) = f(g(x))$$

- How do we compute

$$\frac{dh(x)}{dx} \; ?$$

- Use the chain rule.

The Chain Rule

- Have functions $f, g : \mathbb{R} \to \mathbb{R}$ and define $h : \mathbb{R} \to \mathbb{R}$ as

$$h(x) = (f \circ g)(x) = f(g(x))$$

- Derivative of h w.r.t. x is given by the Chain Rule.

- **Chain Rule**

$$\frac{dh(x)}{dx} = \frac{df(y)}{dy}\frac{dg(x)}{dx} \qquad \text{where } y = g(x)$$

Example of the Chain Rule in action

- Have

$$g(x) = x^2, \qquad f(x) = \sin(x)$$

- One composition of these two functions is

$$h(x) = f(g(x)) = \sin(x^2)$$

- According to the **chain rule**

$$\begin{aligned}
\frac{dh(x)}{dx} &= \frac{df(y)}{dy}\frac{dg(x)}{dx} && \leftarrow \text{where } y = x^2 \\
&= \frac{d\sin(y)}{dy}\frac{dx^2}{dx} \\
&= \cos(y)\,2x \\
&= 2x\cos(x^2) && \leftarrow \text{plug in } y = x^2
\end{aligned}$$

The composition of n functions

- Have functions $f_1, \ldots, f_n : \mathbb{R} \to \mathbb{R}$
- Define function $h : \mathbb{R} \to \mathbb{R}$ as the composition of f_j's

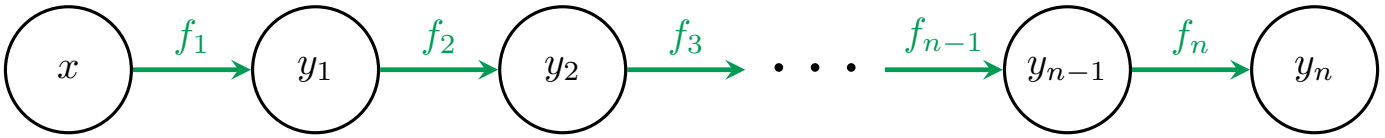
$$h(x) = (f_n \circ f_{n-1} \circ \cdots \circ f_1)(x) = f_n(f_{n-1}(\cdots(f_1(x))\cdots)$$

- Can we compute the derivative

$$\frac{dh(x)}{dx} \quad ?$$

- Yes recursively apply the CHAIN RULE

Computational graph h



- Define

$$g_j = f_n \circ f_{n-1} \circ \cdots \circ f_j$$

- Therefore $g_1 = h$, $g_n = f_n$ and

$$g_j = g_{j+1} \circ f_j \quad \text{for } j = 1, \ldots, n-1$$

- Let $y_j = f_j(y_{j-1})$ and $y_0 = x$ then

$$y_n = g_j(y_{j-1}) \quad \text{for } j = 1, \ldots, n$$

- Apply the **Chain Rule**:
  - For $j = 1, 2, 3, \ldots, n-1$

$$\frac{dy_n}{dy_{j-1}} = \frac{dg_j(y_{j-1})}{dy_{j-1}} = \frac{d\left(g_{j+1} \circ f_j\right)(y_{j-1})}{dy_{j-1}} = \frac{dg_{j+1}(y_j)}{dy_j} \frac{d\, g f_j(y_{j-1})}{dy_{j-1}}$$

$$= \frac{dy_n}{dy_j} \frac{dy_j}{dy_{j-1}}$$

The Chain Rule for the composition of n functions

Recursively applying this fact gives:

$$
\begin{aligned}
\frac{dh(x)}{dx} &= \frac{dg_1(x)}{dx} && \leftarrow \text{Apply } h = g_1 \\
&= \frac{d(g_2 \circ f_1)(x)}{dx} && \leftarrow \text{Apply } g_1 = g_2 \circ f_1 \\
&= \frac{dg_2(y_1)}{dy_1}\frac{df_1(x)}{dx} && \leftarrow \text{Apply chain rule \& } y_1 = f_1(x) \\
&= \frac{d(g_3 \circ f_2)(y_1)}{dy_1}\frac{df_1(x)}{dx} && \leftarrow \text{Apply } g_2 = g_3 \circ f_2 \\
&= \frac{dg_3(y_2)}{dy_2}\frac{df_2(y_1)}{dy_1}\frac{df_1(x)}{dx} && \leftarrow \text{Apply chain rule \& } y_2 = f_2(y_1) \\
&\vdots \\
&= \frac{dg_n(y_{n-1})}{dy_{n-1}}\frac{df_{n-1}(y_{n-2})}{dy_{n-2}}\cdots\frac{df_2(y_1)}{dy_1}\frac{df_1(x)}{dx} \\
&= \frac{df_n(y_{n-1})}{dy_{n-1}}\frac{df_{n-1}(y_{n-2})}{dy_{n-2}}\cdots\frac{df_2(y_1)}{dy_1}\frac{df_1(x)}{dx} && \leftarrow \text{Apply } g_n = f_n
\end{aligned}
$$

where $y_j = (f_j \circ f_{j-1} \circ \cdots \circ f_1)(x) = f_j(y_{j-1})$.

Exploit structure to compute gradient at a point

$$\frac{dh(x)}{dx} = \frac{dy_n}{dx} = \frac{dy_n}{dy_{n-1}} \frac{dy_{n-1}}{dy_{n-2}} \cdots \frac{dy_2}{dy_1} \frac{dy_1}{dx}$$

Computation of $\frac{dh(x)}{dx}$ for $x = x^*$ relies on:

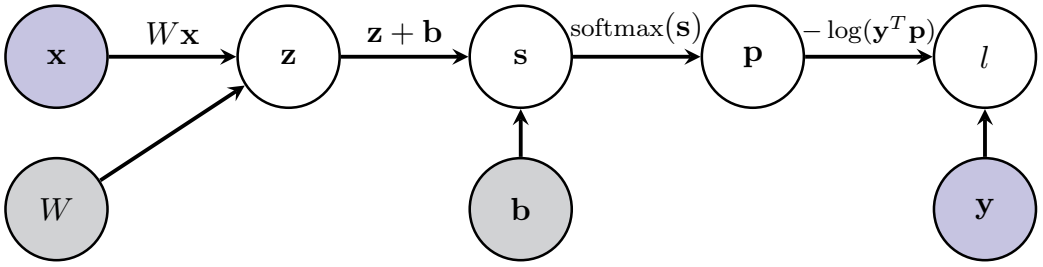
- **Record keeping**: Compute and record values of $y_j^* = f_j(y_{j-1}^*)$'s.
- **Iteratively aggregate** local gradients.
  For $j = n, n-1, \ldots, 2$
  - Compute local derivative: $\left.\frac{df_j(y_{j-1})}{dy_{j-1}}\right|_{y_{j-1}=y_{j-1}^*}$
  - Aggregate:

$$\left.\frac{dy_n^*}{dy_{j-1}}\right|_{y_{j-1}=y_{j-1}^*} = \left.\frac{dy_n^*}{dy_j}\right|_{y_j=y_j^*} \times \left.\frac{df_j(y_{j-1})}{dy_{j-1}}\right|_{y_{j-1}=y_{j-1}^*}$$

Remember $\frac{dy_n}{dy_{j+1}} = \frac{dy_n}{dy_{n-1}} \frac{dy_{n-1}}{dy_{n-2}} \cdots \frac{dy_{j+2}}{dy_{j+1}}$

This is Backprop algorithm given a chain dependency between the y_j's.

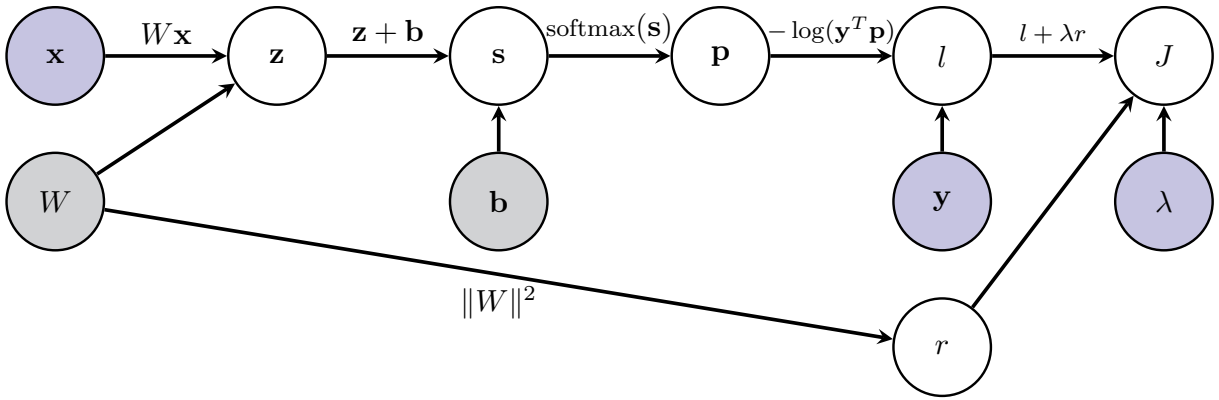
Problem 1: But what if I don't have a chain?



- This computational graph is **not a chain**.
- Some nodes have **multiple parents**.
- The function represented by graph is

$$l(\mathbf{x}, \mathbf{y}, W, \mathbf{b}) = -\log(\mathbf{y}^T \mathrm{Softmax}(W\mathbf{x} + \mathbf{b}))$$

Problem 1a: And when a regularization term is added..

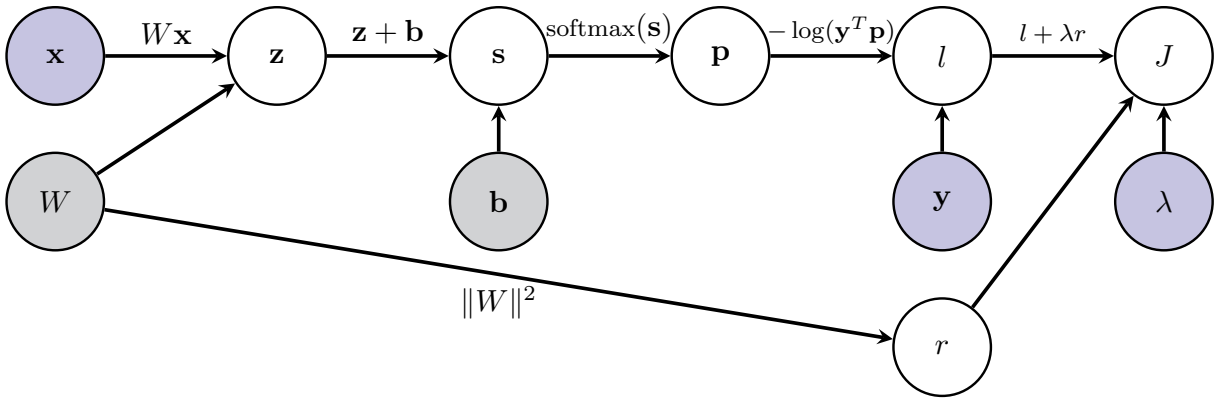


- This computational graph is **not a chain**.
- Some nodes have **multiple parents** and others **multiple children**.
- The function represented by graph is

$$J(\mathbf{x},\mathbf{y},W,\mathbf{b},\lambda) = -\log(\mathbf{y}^T\mathsf{Softmax}(W\mathbf{x}+\mathbf{b})) + \lambda\sum_{i,j} W_{i,j}^2$$

- How is the back-propagation algorithm defined in these cases?

Problem 1a: And when a regularization term is added..



- This computational graph is **not a chain**.
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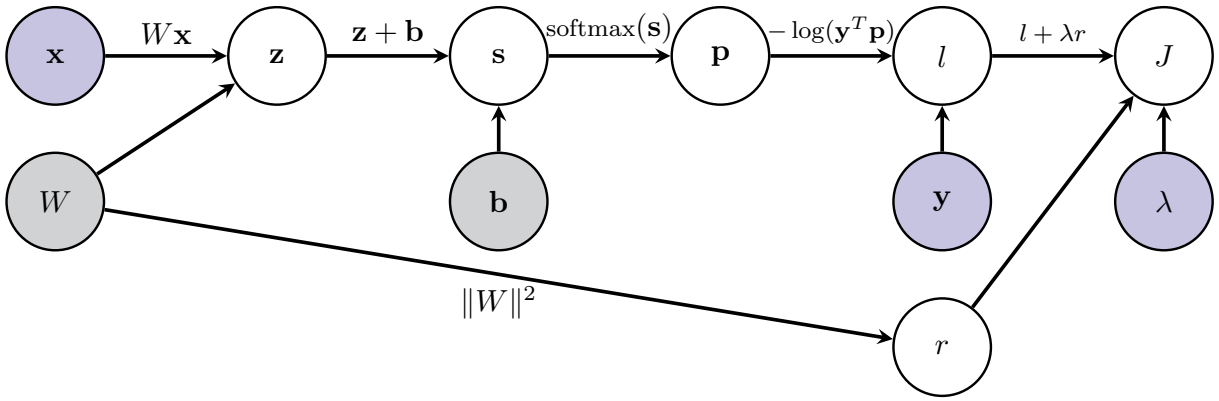
- How is the back-propagation algorithm defined in these cases?

Problem 2: Don't have scalar inputs and outputs



- The function represented by graph:

$$J(\mathbf{x}, \mathbf{y}, W, \mathbf{b}, \lambda) = -\log(\mathbf{y}^T \mathrm{Softmax}(W\mathbf{x} + \mathbf{b})) + \lambda \sum_{i,j} W_{i,j}^2$$

- Nearly all of the inputs and intermediary outputs are **vectors** or **matrices**.

- How are the derivatives defined in this case?

Chain Rule for functions with vector inputs and vector outputs

Chain Rule for vector input and output

- Have two functions $g : \mathbb{R}^d \to \mathbb{R}^m$ and $f : \mathbb{R}^m \to \mathbb{R}^c$.
- Define $h : \mathbb{R}^d \to \mathbb{R}^c$ as the composition of f and g:

$$h(\mathbf{x}) = (f \circ g)(\mathbf{x}) = f(g(\mathbf{x}))$$

- Consider

$$\frac{\partial h(\mathbf{x})}{\partial \mathbf{x}}$$

- How is it defined and computed?
- What's the chain rule for vector valued functions?

Chain Rule for vector input and output

- Let $\mathbf{y} = h(\mathbf{x})$ where each $h : \mathbb{R}^d \to \mathbb{R}^c$ then

$$\frac{\partial h(\mathbf{x})}{\partial \mathbf{x}} = \frac{\partial \mathbf{y}}{\partial \mathbf{x}} = \begin{pmatrix} \frac{\partial y_1}{\partial x_1} & \cdots & \frac{\partial y_1}{\partial x_d} \\ \frac{\partial y_2}{\partial x_1} & \cdots & \frac{\partial y_2}{\partial x_d} \\ \vdots & \vdots & \vdots \\ \frac{\partial y_c}{\partial x_1} & \cdots & \frac{\partial y_c}{\partial x_d} \end{pmatrix} \quad \leftarrow \text{this is a Jacobian matrix}$$

  and is a matrix of size $c \times d$.

- **Chain Rule** says if $h = f \circ g$ ($g : \mathbb{R}^d \to \mathbb{R}^m$ and $f : \mathbb{R}^m \to \mathbb{R}^c$) then

$$\frac{\partial h(\mathbf{x})}{\partial \mathbf{x}} = \frac{\partial \mathbf{y}}{\partial \mathbf{x}} = \frac{\partial \mathbf{y}}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{x}}$$

  where $\mathbf{z} = g(\mathbf{x})$ and $\mathbf{y} = f(\mathbf{z})$.

- Both $\frac{\partial \mathbf{y}}{\partial \mathbf{z}}$ $(c \times m)$ and $\frac{\partial \mathbf{z}}{\partial \mathbf{x}}$ $(m \times d)$ defined slly to $\frac{\partial \mathbf{y}}{\partial \mathbf{x}}$.

Chain Rule for vector input and scalar output

The cost functions we will examine usually have a scalar output

- Let $\mathbf{x} \in \mathbb{R}^d$, $f : \mathbb{R}^d \to \mathbb{R}^m$ and $g : \mathbb{R}^m \to \mathbb{R}$

$$\mathbf{z} = f(\mathbf{x})$$
$$s = g(\mathbf{z})$$

- The **Chain Rule** says gradient of output w.r.t. input

$$\frac{\partial s}{\partial \mathbf{x}} = \begin{pmatrix} \frac{\partial s}{\partial x_1} & \cdots & \frac{\partial s}{\partial x_d} \end{pmatrix}$$

is given by a gradient times a Jacobian:

$$\frac{\partial s}{\partial \mathbf{x}} = \underbrace{\frac{\partial s}{\partial \mathbf{z}}}_{1 \times m} \underbrace{\frac{\partial \mathbf{z}}{\partial \mathbf{x}}}_{m \times d}$$

where

$$\frac{\partial \mathbf{z}}{\partial \mathbf{x}} = \begin{pmatrix} \frac{\partial z_1}{\partial x_1} & \cdots & \frac{\partial z_1}{\partial x_d} \\ \frac{\partial z_2}{\partial x_1} & \cdots & \frac{\partial z_2}{\partial x_d} \\ \vdots & \vdots & \vdots \\ \frac{\partial z_m}{\partial x_1} & \cdots & \frac{\partial z_m}{\partial x_d} \end{pmatrix}$$

Two intermediary vector inputs and scalar output

- $f_1 : \mathbb{R}^d \to \mathbb{R}^{m_1}, f_2 : \mathbb{R}^d \to \mathbb{R}^{m_2}$ and $g : \mathbb{R}^n \to \mathbb{R}$ $(n = m_1 + m_2)$

$$\mathbf{z}_1 = f_1(\mathbf{x}), \qquad \mathbf{z}_2 = f_2(\mathbf{x})$$

$$s = g(\mathbf{z}_1, \mathbf{z}_2) = g(\mathbf{v}) \qquad \text{where } \mathbf{v} = \begin{pmatrix} \mathbf{z}_1 \\ \mathbf{z}_2 \end{pmatrix}.$$

- **Chain Rule** says gradient of the output w.r.t. the input

$$\frac{\partial s}{\partial \mathbf{x}} = \begin{pmatrix} \frac{\partial s}{\partial x_1} & \cdots & \frac{\partial s}{\partial x_d} \end{pmatrix}$$

is given by:

$$\frac{\partial s}{\partial \mathbf{x}} = \underbrace{\frac{\partial s}{\partial \mathbf{v}}}_{1 \times n} \underbrace{\frac{\partial \mathbf{v}}{\partial \mathbf{x}}}_{n \times d}$$

But

$$\frac{\partial s}{\partial \mathbf{v}} = \begin{pmatrix} \frac{\partial s}{\partial \mathbf{z}_1} & \frac{\partial s}{\partial \mathbf{z}_2} \end{pmatrix} \quad \text{and} \quad \frac{\partial \mathbf{v}}{\partial \mathbf{x}} = \begin{pmatrix} \frac{\partial \mathbf{z}_1}{\partial \mathbf{x}} \\ \frac{\partial \mathbf{z}_2}{\partial \mathbf{x}} \end{pmatrix}$$

$\Longrightarrow$

$$\frac{\partial s}{\partial \mathbf{x}} = \frac{\partial s}{\partial \mathbf{v}} \frac{\partial \mathbf{v}}{\partial \mathbf{x}} = \underbrace{\frac{\partial s}{\partial \mathbf{z}_1}}_{1 \times m_1} \underbrace{\frac{\partial \mathbf{z}_1}{\partial \mathbf{x}}}_{m_1 \times d} + \underbrace{\frac{\partial s}{\partial \mathbf{z}_2}}_{1 \times m_2} \underbrace{\frac{\partial \mathbf{z}_2}{\partial \mathbf{x}}}_{m_2 \times d}$$

More generally

- $f_i : \mathbb{R}^d \to \mathbb{R}^{m_i}$ for $i = 1, \ldots, t$ and $g : \mathbb{R}^n \to \mathbb{R}$ $(n = m_1 + \cdots + m_t)$

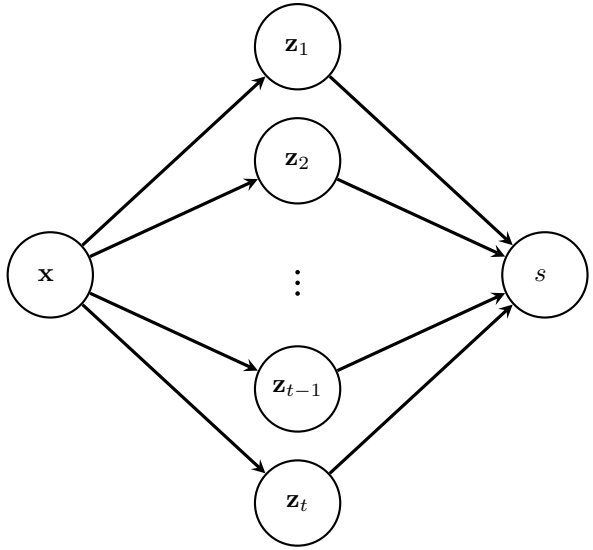
$$\mathbf{z}_i = f_i(\mathbf{x}), \qquad \text{for } i = 1, \ldots, t$$
$$s = g(\mathbf{z}_1, \ldots, \mathbf{z}_t)$$

- Consequence of the **Chain Rule**

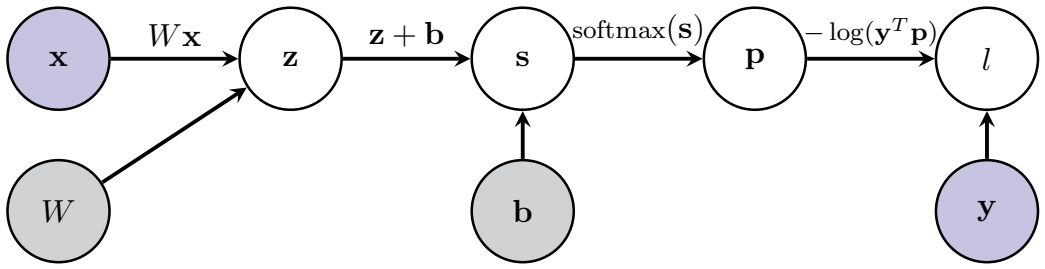
$$\frac{\partial s}{\partial \mathbf{x}} = \sum_{i=1}^{t} \frac{\partial s}{\partial \mathbf{z}_i} \frac{\partial \mathbf{z}_i}{\partial \mathbf{x}}$$

- Computational graph interpretation. Let $\mathcal{C}_{\mathbf{x}}$ be the children nodes of $\mathbf{x}$ then

$$\frac{\partial s}{\partial \mathbf{x}} = \sum_{\mathbf{z} \in \mathcal{C}_{\mathbf{x}}} \frac{\partial s}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{x}}$$



Issues we need to sort out



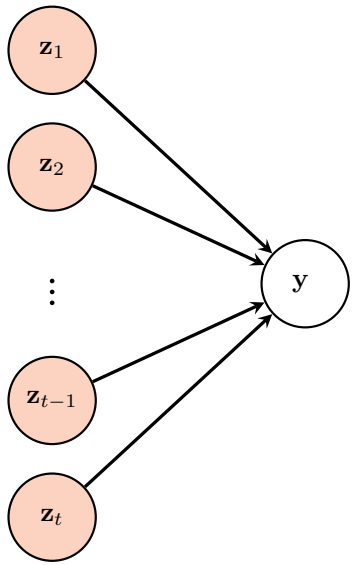
- Back-propagation when the computational graph is **not a chain**.
- Derivative computations when the inputs and outputs are not scalars. ✓
- Will now describe Back-prop for non-chains.

Back-propagation for non-chain computational graphs

Results that we need

- Have node $\mathbf{y}$.
- Denote the set of $\mathbf{y}$'s parent nodes by $\mathcal{P}_{\mathbf{y}}$ and their values by

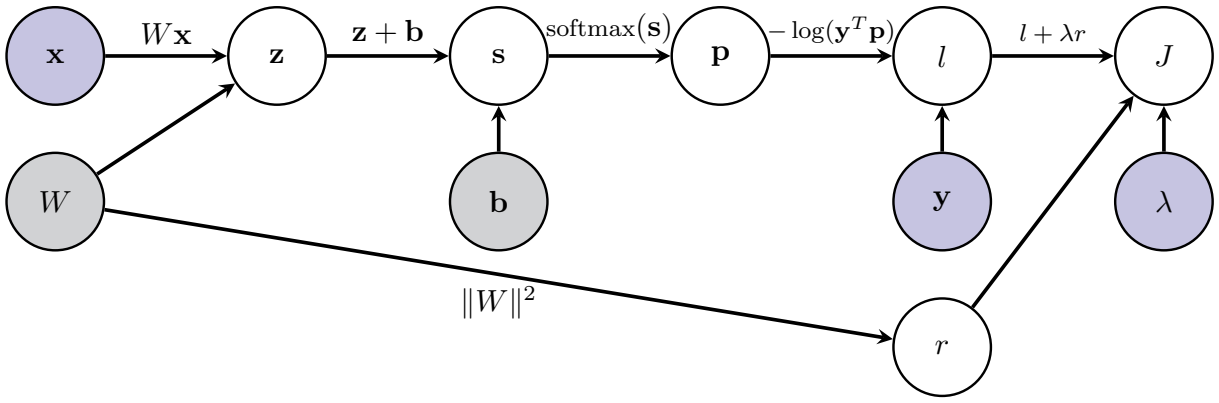
$$V_{\mathcal{P}_{\mathbf{y}}} = \{\mathbf{z}.\text{value} \mid \mathbf{z} \in \mathcal{P}_{\mathbf{y}}\}$$



- Given $V_{\mathcal{P}_{\mathbf{y}}}$ can now apply the function $f_{\mathbf{z}}$

$$\mathbf{y}.\text{value} = f_{\mathbf{y}}(V_{\mathcal{P}_{\mathbf{y}}})$$

Results that we need but already know



- Consider node W in the above graph. Its children are $\{\mathbf{z}, r\}$. Applying the chain rule

$$\frac{\partial J}{\partial W} = \frac{\partial J}{\partial r}\frac{\partial r}{\partial W} + \frac{\partial J}{\partial \mathbf{z}}\frac{\partial \mathbf{z}}{\partial W}$$

- In general for node $\mathbf{c}$ with children specified by $\mathcal{C}_\mathbf{c}$:

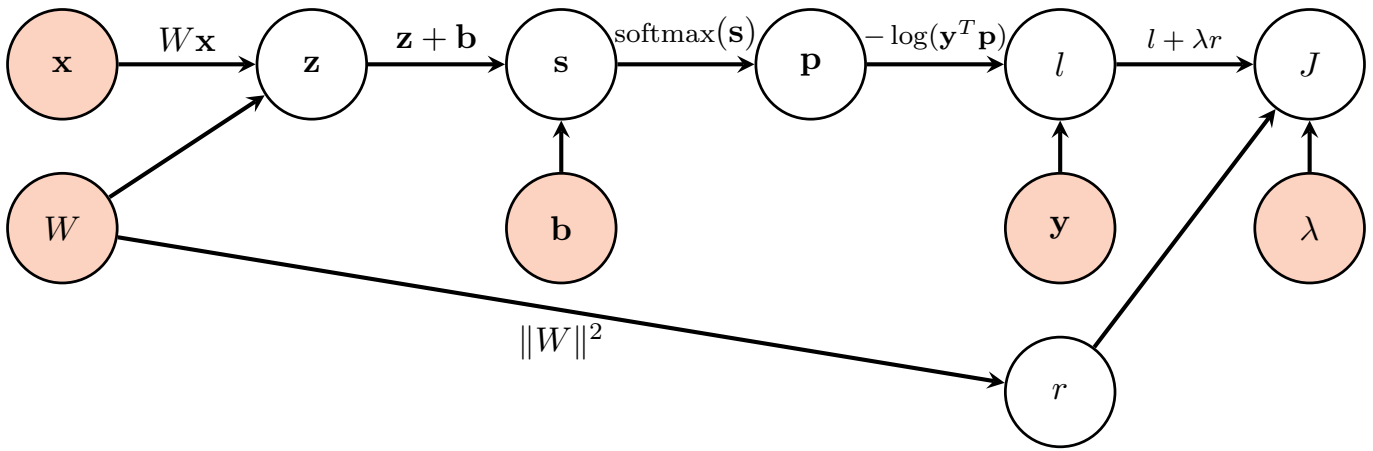
$$\frac{\partial J}{\partial \mathbf{c}} = \sum_{\mathbf{u}\in\mathcal{C}_\mathbf{c}} \frac{\partial J}{\partial \mathbf{u}}\frac{\partial \mathbf{u}}{\partial \mathbf{c}}$$

Pseudo-Code for the Generic Forward Pass

```
procedure EvaulateGraphFn(G)                          ▷ G is the computational graph
    S = GetStartNodes(G)                              ▷ a start node has no parent and its value is already set
    for s ∈ S do
        ComputeBranch(s, G)
    end for
end procedure

procedure ComputeBranch(s, G)                         ▷ recursive fn evaluating nodes
    C_s = GetChildren(s, G)
    for each n ∈ C_s do                               ▷ Try to evaluate each children node
        if !n.computed then                           ▷ Unless child is already computed
            P_n = GetParents(n, G)
            if CheckAllNodesComputed(P_n) then        ▷ Or not all parents of children are computed
                f_n = GetNodeFn(n)
                n.value = f_n(P_n)
                n.computed = true
                ComputeBranch(n, G)
            end if
        end if
    end for
end procedure
```

Identify Start Nodes

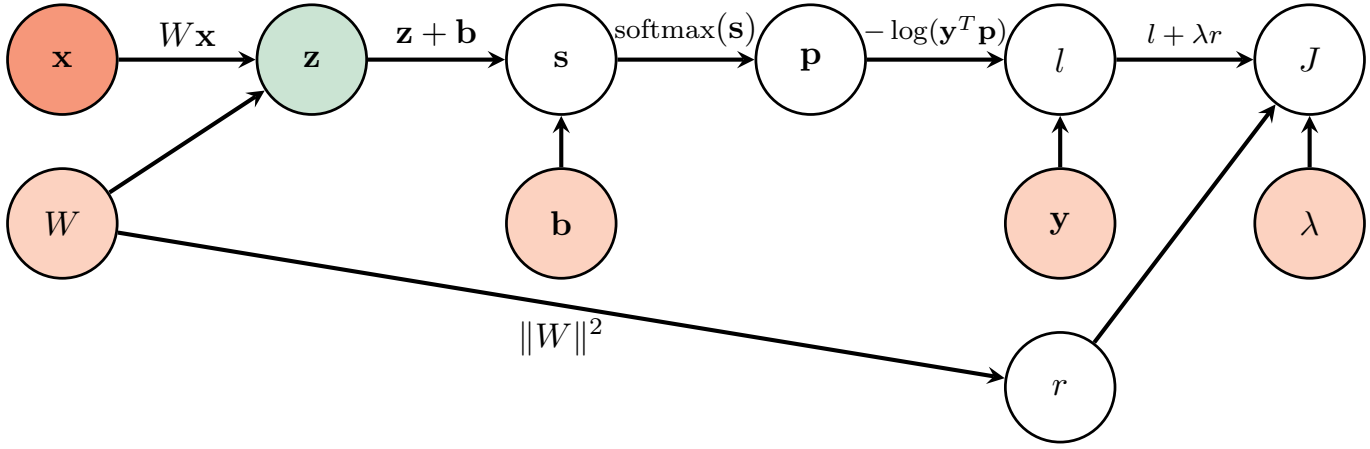


procedure EVAULATEGRAPHFN(G) ▷ G is the computational graph
  $\mathcal{S}$ = GetStartNodes(G)
  for $\mathbf{s} \in \mathcal{S}$ **do**
    ComputeBranch($\mathbf{s}$, G)
  end for
end procedure

procedure COMPUTEBRANCH($\mathbf{s}$, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren($\mathbf{s}$, G)
  for each $\mathbf{n} \in \mathcal{C}_\mathbf{s}$ **do**
    if !$\mathbf{n}$.computed **then**
      $\mathcal{P}_\mathbf{n}$ = GetParents($\mathbf{n}$, G)
      if CheckAllNodesComputed($\mathcal{P}_\mathbf{n}$) **then**
        $f_\mathbf{n}$ = GetNodeFn($\mathbf{n}$)
        $\mathbf{n}$.value = $f_\mathbf{n}(\mathcal{P}_\mathbf{n})$
        $\mathbf{n}$.computed = true
        ComputeBranch($\mathbf{n}$, G)
      end if
    end if
  end for
end procedure

Generic Forward Pass

Order in which nodes are evaluated



procedure EVAULATEGRAPHFN(G) ▷ G is the computational graph
  $\mathcal{S}$ = GetStartNodes(G)
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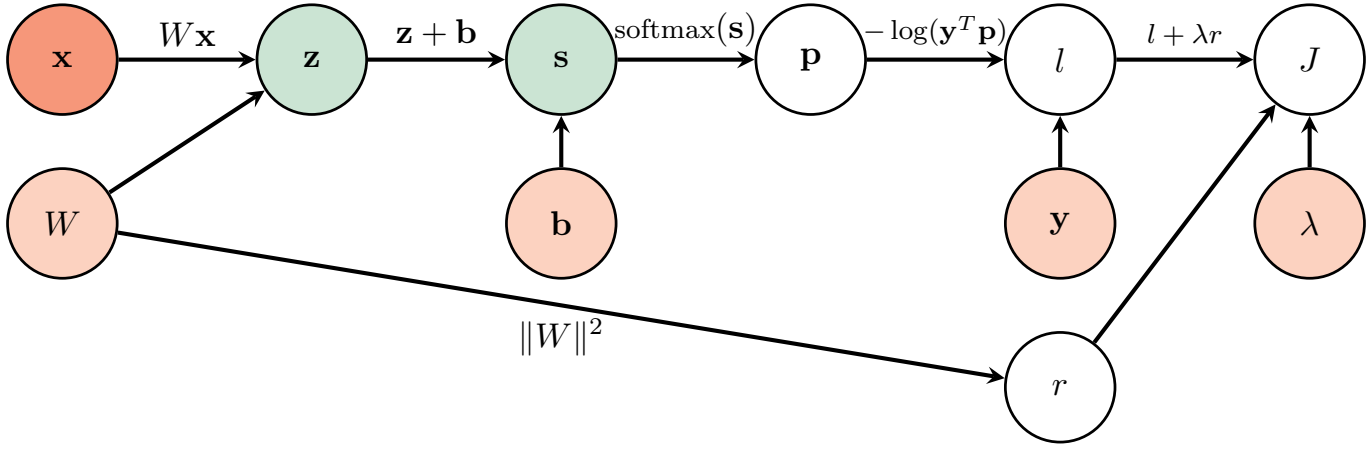
    ComputeBranch($\mathbf{s}$, G)
  end for
end procedure

procedure COMPUTEBRANCH($\mathbf{s}$, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren($\mathbf{s}$, G)
  for each $\mathbf{n} \in \mathcal{C}_\mathbf{s}$ **do**
    if !$\mathbf{n}$.computed **then**
      $\mathcal{P}_\mathbf{n}$ = GetParents($\mathbf{n}$, G)
      if CheckAllNodesComputed($\mathcal{P}_\mathbf{n}$) **then**
        $f_\mathbf{n}$ = GetNodeFn($\mathbf{n}$)
        $\mathbf{n}$.value = $f_\mathbf{n}(\mathcal{P}_\mathbf{n})$
        $\mathbf{n}$.computed = true
        ComputeBranch($\mathbf{n}$, G)
      end if
    end if
  end for
end procedure

Generic Forward Pass

Order in which nodes are evaluated

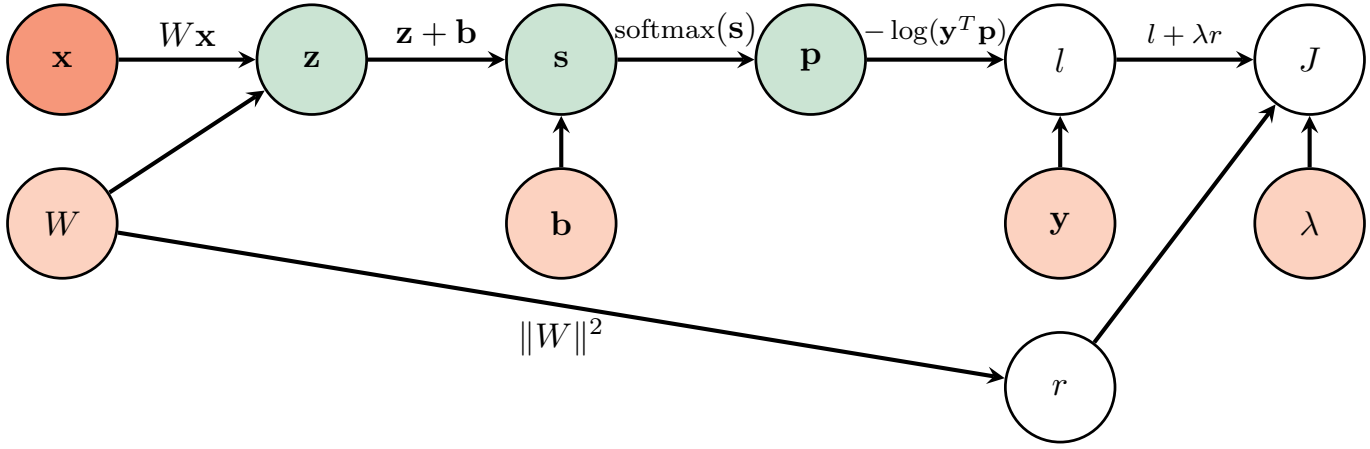


procedure EVAULATEGRAPHFN(G) ▷ G is the computational graph
  $\mathcal{S}$ = GetStartNodes(G)
  for $\mathbf{s} \in \mathcal{S}$ **do**
    ComputeBranch($\mathbf{s}$, G)
  end for
end procedure

procedure COMPUTEBRANCH($\mathbf{s}$, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren($\mathbf{s}$, G)
  for each $\mathbf{n} \in \mathcal{C}_\mathbf{s}$ **do**
    if !$\mathbf{n}$.computed **then**
      $\mathcal{P}_\mathbf{n}$ = GetParents($\mathbf{n}$, G)
      if CheckAllNodesComputed($\mathcal{P}_\mathbf{n}$) **then**
        $f_\mathbf{n}$ = GetNodeFn($\mathbf{n}$)
        $\mathbf{n}$.value = $f_\mathbf{n}(\mathcal{P}_\mathbf{n})$
        $\mathbf{n}$.computed = true
        ComputeBranch($\mathbf{n}$, G)
      end if
    end if
  end for
end procedure

Generic Forward Pass

Order in which nodes are evaluated

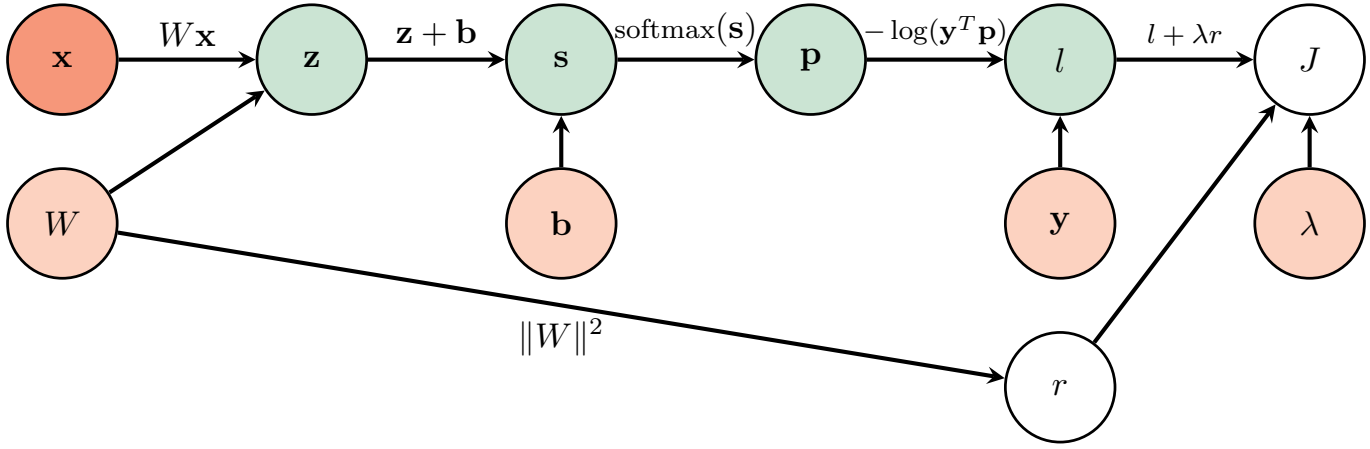


procedure EVAULATEGRAPHFN(G) ▷ G is the computational graph
  $\mathcal{S}$ = GetStartNodes(G)
  for $\mathbf{s} \in \mathcal{S}$ **do**
    ComputeBranch($\mathbf{s}$, G)
  end for
end procedure

procedure COMPUTEBRANCH($\mathbf{s}$, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren($\mathbf{s}$, G)
  for each $\mathbf{n} \in \mathcal{C}_\mathbf{s}$ **do**
    if !$\mathbf{n}$.computed **then**
      $\mathcal{P}_\mathbf{n}$ = GetParents($\mathbf{n}$, G)
      if CheckAllNodesComputed($\mathcal{P}_\mathbf{n}$) **then**
        $f_\mathbf{n}$ = GetNodeFn($\mathbf{n}$)
        $\mathbf{n}$.value = $f_\mathbf{n}(\mathcal{P}_\mathbf{n})$
        $\mathbf{n}$.computed = true
        ComputeBranch($\mathbf{n}$, G)
      end if
    end if
  end for
end procedure

Generic Forward Pass

Order in which nodes are evaluated

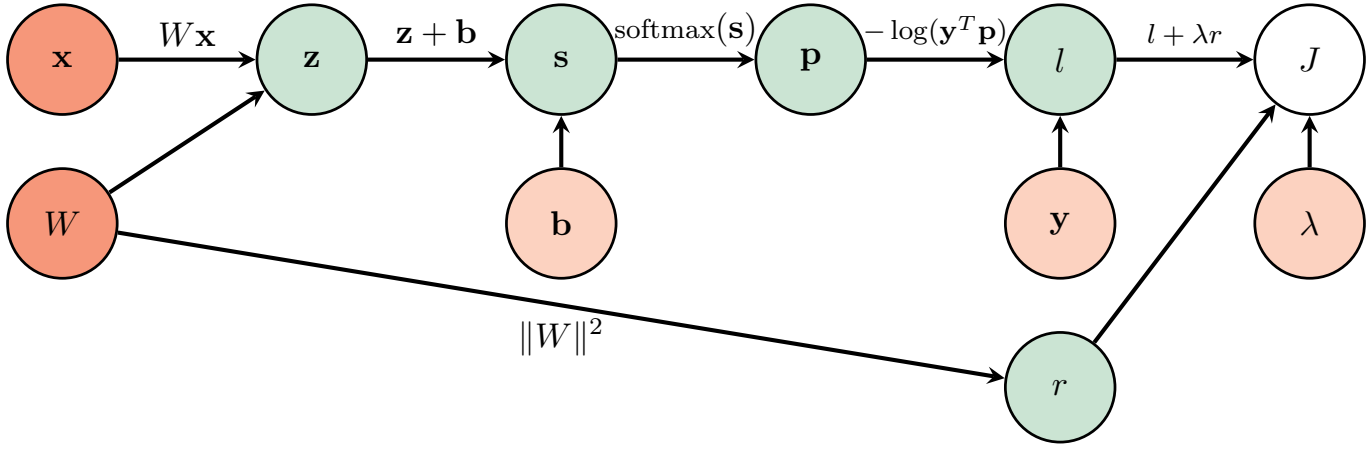


procedure EVAULATEGRAPHFN(G) ▷ G is the computational graph
  $\mathcal{S}$ = GetStartNodes(G)
  for $\mathbf{s} \in \mathcal{S}$ **do**
    ComputeBranch($\mathbf{s}$, G)
  end for
end procedure

procedure COMPUTEBRANCH($\mathbf{s}$, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren($\mathbf{s}$, G)
  for each $\mathbf{n} \in \mathcal{C}_\mathbf{s}$ **do**
    if !$\mathbf{n}$.computed **then**
      $\mathcal{P}_\mathbf{n}$ = GetParents($\mathbf{n}$, G)
      if CheckAllNodesComputed($\mathcal{P}_\mathbf{n}$) **then**
        $f_\mathbf{n}$ = GetNodeFn($\mathbf{n}$)
        $\mathbf{n}$.value = $f_\mathbf{n}(\mathcal{P}_\mathbf{n})$
        $\mathbf{n}$.computed = true
        ComputeBranch($\mathbf{n}$, G)
      end if
    end if
  end for
end procedure

Generic Forward Pass

Order in which nodes are evaluated

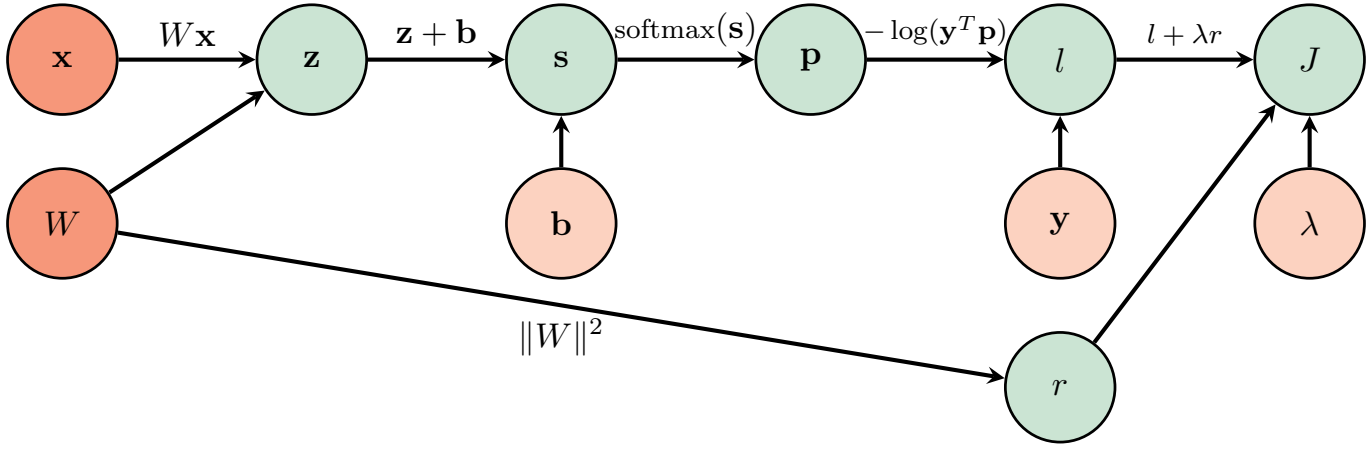


procedure EVAULATEGRAPHFN(G) ▷ G is the computational graph
  $\mathcal{S}$ = GetStartNodes(G)
  for $\mathbf{s} \in \mathcal{S}$ **do**
    ComputeBranch($\mathbf{s}$, G)
  end for
end procedure

procedure COMPUTEBRANCH($\mathbf{s}$, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren($\mathbf{s}$, G)
  for each $\mathbf{n} \in \mathcal{C}_\mathbf{s}$ **do**
    if !$\mathbf{n}$.computed **then**
      $\mathcal{P}_\mathbf{n}$ = GetParents($\mathbf{n}$, G)
      if CheckAllNodesComputed($\mathcal{P}_\mathbf{n}$) **then**
        $f_\mathbf{n}$ = GetNodeFn($\mathbf{n}$)
        $\mathbf{n}$.value = $f_\mathbf{n}(\mathcal{P}_\mathbf{n})$
        $\mathbf{n}$.computed = true
        ComputeBranch($\mathbf{n}$, G)
      end if
    end if
  end for
end procedure

Generic Forward Pass

Order in which nodes are evaluated



procedure EVAULATEGRAPHFN(G) ▷ G is the computational graph
  $\mathcal{S}$ = GetStartNodes(G)
  for $\mathbf{s} \in \mathcal{S}$ **do**
    ComputeBranch($\mathbf{s}$, G)
  end for
end procedure

procedure COMPUTEBRANCH($\mathbf{s}$, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren($\mathbf{s}$, G)
  for each $\mathbf{n} \in \mathcal{C}_\mathbf{s}$ **do**
    if !$\mathbf{n}$.computed **then**
      $\mathcal{P}_\mathbf{n}$ = GetParents($\mathbf{n}$, G)
      if CheckAllNodesComputed($\mathcal{P}_\mathbf{n}$) **then**
        $f_\mathbf{n}$ = GetNodeFn($\mathbf{n}$)
        $\mathbf{n}$.value = $f_\mathbf{n}(\mathcal{P}_\mathbf{n})$
        $\mathbf{n}$.computed = true
        ComputeBranch($\mathbf{n}$, G)
      end if
    end if
  end for
end procedure

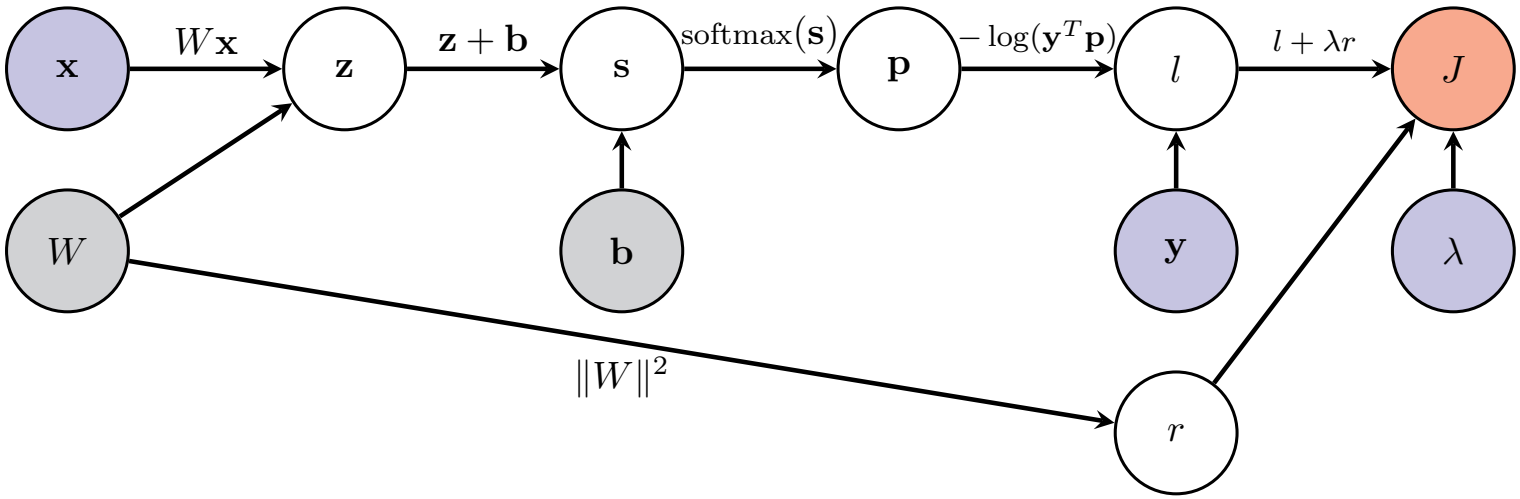
Pseudo-Code for the Generic Backward Pass

procedure PERFORMBACKPASS(G)
    J = GetResultNode(G) ▷ node with the value of cost function
    BackOp(J, G) ▷ Start the Backward-pass
end procedure

procedure BACKOP($\mathbf{s}$, G)
    $\mathcal{C}_\mathbf{s}$ = GetChildren($\mathbf{s}$, G)
    if $\mathcal{C}_\mathbf{s} = \emptyset$ **then** ▷ At the result node
        $\mathbf{s}$.Grad = 1
    end if
    if AllGradientsComputed($\mathcal{C}_\mathbf{s}$) **then** ▷ Have computed all $\frac{\partial J}{\partial \mathbf{c}}$ where $\mathbf{c} \in \mathcal{C}_\mathbf{s}$
        $\mathbf{s}$.Grad = $\mathbf{0}$
        for each $\mathbf{c} \in \mathcal{C}_\mathbf{s}$ **do**
            $\mathbf{s}$.Grad += $\mathbf{c}$.Grad * $\mathbf{c}.\mathbf{s}$.Jacobian ▷ $\frac{\partial J}{\partial \mathbf{s}} \mathrel{+}= \frac{\partial J}{\partial \mathbf{c}} \frac{\partial \mathbf{c}}{\partial \mathbf{s}}$
        end for
        $\mathbf{s}$.GradComputed = true
    end if
    for each $\mathbf{p} \in \mathcal{P}_\mathbf{s}$ **do** ▷ Compute the Jacobian of $f_\mathbf{s}$ w.r.t. each parent node
        $\mathbf{s}.\mathbf{p}$.Jacobian = $\frac{\partial f_\mathbf{p}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}}$ ▷ $\frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}} = \frac{\partial \mathbf{s}}{\partial \mathbf{p}}$
        BackOp($\mathbf{p}$, G)
    end for
end procedure

Generic Backward Pass: Order of computations

Identify Result Node

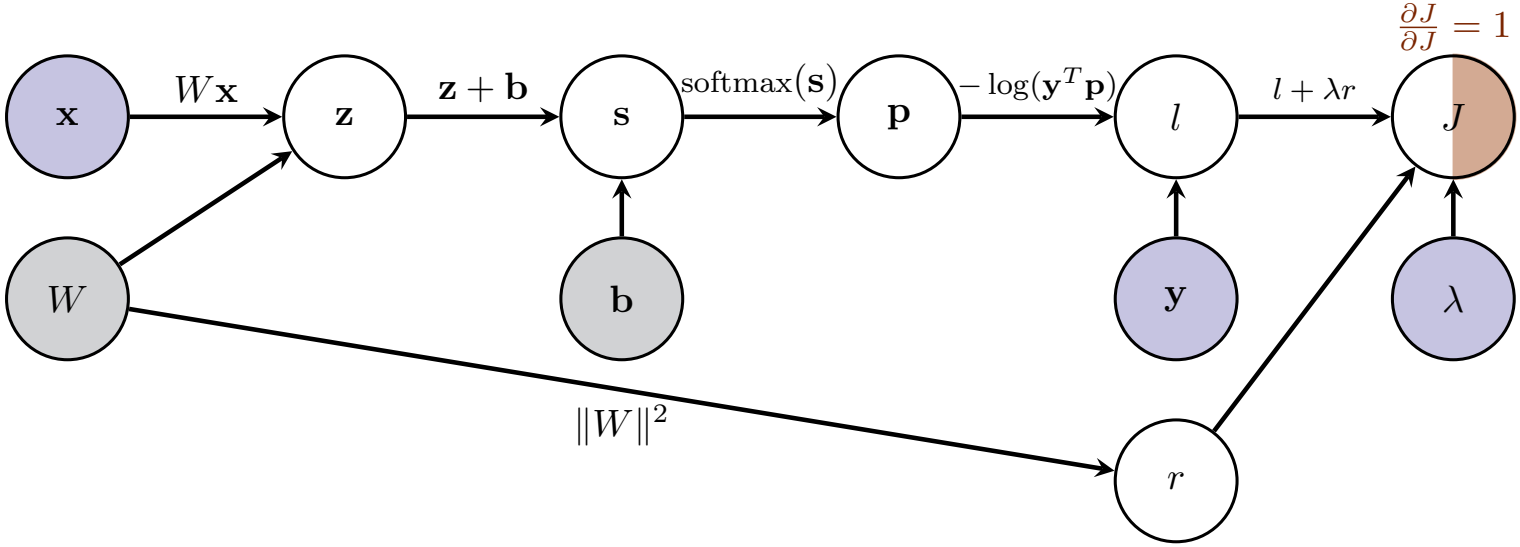


procedure PERFORMBACKPASS(G)
  J = GetResultNode(G) ▷ node with the value of cost function
  BackOp(J, G) ▷ Start the Backward-pass
end procedure

procedure BACKOP($\mathbf{s}$, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren($\mathbf{s}$, G)
  if $\mathcal{C}_\mathbf{s} = \emptyset$ **then** ▷ At the result node
    $\mathbf{s}$.Grad = 1
  else
    if AllGradientsComputed($\mathcal{C}_\mathbf{s}$) **then** ▷ All $\frac{\partial J}{\partial \mathbf{c}}$ computed where $\mathbf{c} \in \mathcal{C}_\mathbf{s}$
      $\mathbf{s}$.Grad = $\mathbf{0}$
      for each $\mathbf{c} \in \mathcal{C}_\mathbf{s}$ **do**
        $\mathbf{s}$.Grad += $\mathbf{c}$.Grad * $\mathbf{c}$.$\mathbf{s}$.Jacobian ▷ $\frac{\partial J}{\partial \mathbf{s}} \mathrel{+}= \frac{\partial J}{\partial \mathbf{c}} \frac{\partial \mathbf{c}}{\partial \mathbf{s}}$
      end for
      $\mathbf{s}$.GradComputed = true
    end if
  end if
  for each $\mathbf{p} \in \mathcal{P}_\mathbf{s}$ **do** ▷ Compute Jacobian of $f_\mathbf{s}$ w.r.t. each parent node
    $\mathbf{s}.\mathbf{p}.\text{Jacobian} = \frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}}$ ▷ $\frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}} = \frac{\partial \mathbf{s}}{\partial \mathbf{p}}$
    BackOp($\mathbf{p}$, G)
  end for
end procedure

Generic Backward Pass: Order of computations

Compute Gradient of current node

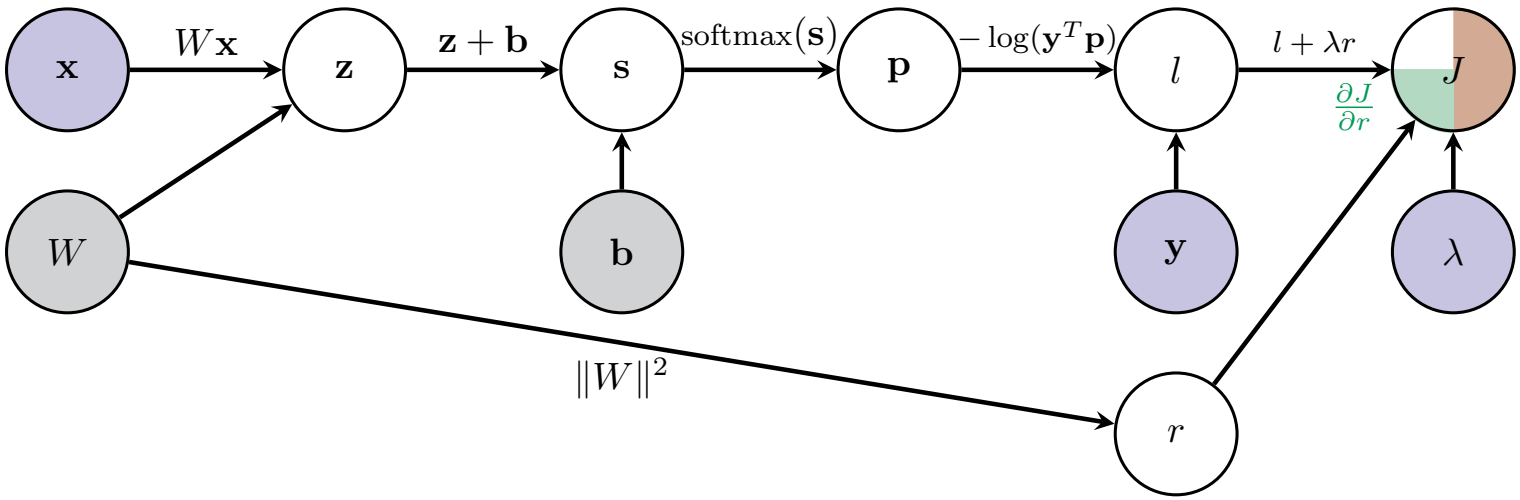


procedure PERFORMBACKPASS(G)
  J = GetResultNode(G) ▷ node with the value of cost function
  BackOp(J, G) ▷ Start the Backward-pass
end procedure

procedure BACKOP($\mathbf{s}$, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren($\mathbf{s}$, G)
  if $\mathcal{C}_\mathbf{s} = \emptyset$ **then** ▷ At the result node
    $\mathbf{s}$.Grad = 1
  else
    if AllGradientsComputed($\mathcal{C}_\mathbf{s}$) **then** ▷ All $\frac{\partial J}{\partial \mathbf{c}}$ computed where $\mathbf{c} \in \mathcal{C}_\mathbf{s}$
      $\mathbf{s}$.Grad = $\mathbf{0}$
      for each $\mathbf{c} \in \mathcal{C}_\mathbf{s}$ **do**
        $\mathbf{s}$.Grad += $\mathbf{c}$.Grad * $\mathbf{c}$.$\mathbf{s}$.Jacobian ▷ $\frac{\partial J}{\partial \mathbf{s}}$ += $\frac{\partial J}{\partial \mathbf{c}} \frac{\partial \mathbf{c}}{\partial \mathbf{s}}$
      end for
      $\mathbf{s}$.GradComputed = true
    end if
  end if
  for each $\mathbf{p} \in \mathcal{P}_\mathbf{s}$ **do** ▷ Compute Jacobian of $f_\mathbf{s}$ w.r.t. each parent node
    $\mathbf{s}$.$\mathbf{p}$.Jacobian = $\frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}}$ ▷ $\frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}} = \frac{\partial \mathbf{s}}{\partial \mathbf{p}}$
    BackOp($\mathbf{p}$, G)
  end for
end procedure

Generic Backward Pass: Order of computations

Compute Jacobian of current node w.r.t. one parent

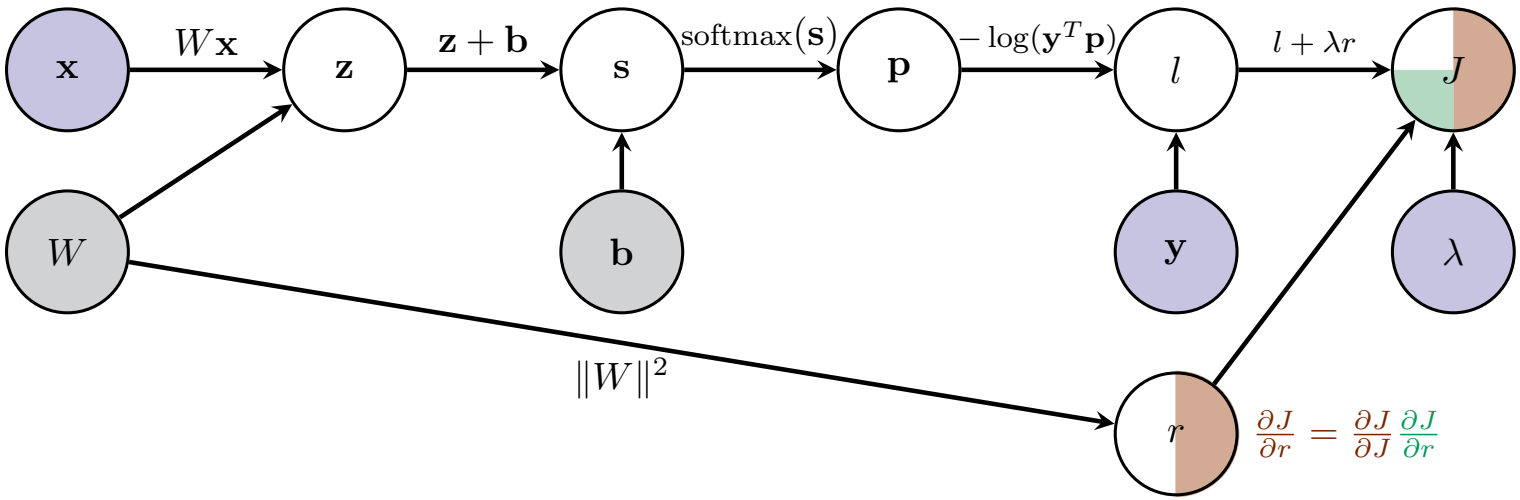


procedure PERFORMBACKPASS(G)
  J = GetResultNode(G) ▷ node with the value of cost function
  BackOp(J, G) ▷ Start the Backward-pass
end procedure

procedure BACKOP($\mathbf{s}$, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren($\mathbf{s}$, G)
  if $\mathcal{C}_\mathbf{s} = \emptyset$ **then** ▷ At the result node
    $\mathbf{s}$.Grad = 1
  else
    if AllGradientsComputed($\mathcal{C}_\mathbf{s}$) **then** ▷ All $\frac{\partial J}{\partial \mathbf{c}}$ computed where $\mathbf{c} \in \mathcal{C}_\mathbf{s}$
      $\mathbf{s}$.Grad = $\mathbf{0}$
      for each $\mathbf{c} \in \mathcal{C}_\mathbf{s}$ **do**
        $\mathbf{s}$.Grad += $\mathbf{c}$.Grad * $\mathbf{c}$.$\mathbf{s}$.Jacobian ▷ $\frac{\partial J}{\partial \mathbf{s}} \mathrel{+}= \frac{\partial J}{\partial \mathbf{c}} \frac{\partial \mathbf{c}}{\partial \mathbf{s}}$
      end for
      $\mathbf{s}$.GradComputed = true
    end if
  end if
  for each $\mathbf{p} \in \mathcal{P}_\mathbf{s}$ **do** ▷ Compute Jacobian of $f_\mathbf{s}$ w.r.t. each parent node
    $\mathbf{s}.\mathbf{p}.\text{Jacobian} = \frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}}$ ▷ $\frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}} = \frac{\partial \mathbf{s}}{\partial \mathbf{p}}$
    BackOp($\mathbf{p}$, G)
  end for
end procedure

Generic Backward Pass: Order of computations

Compute Gradient of current node

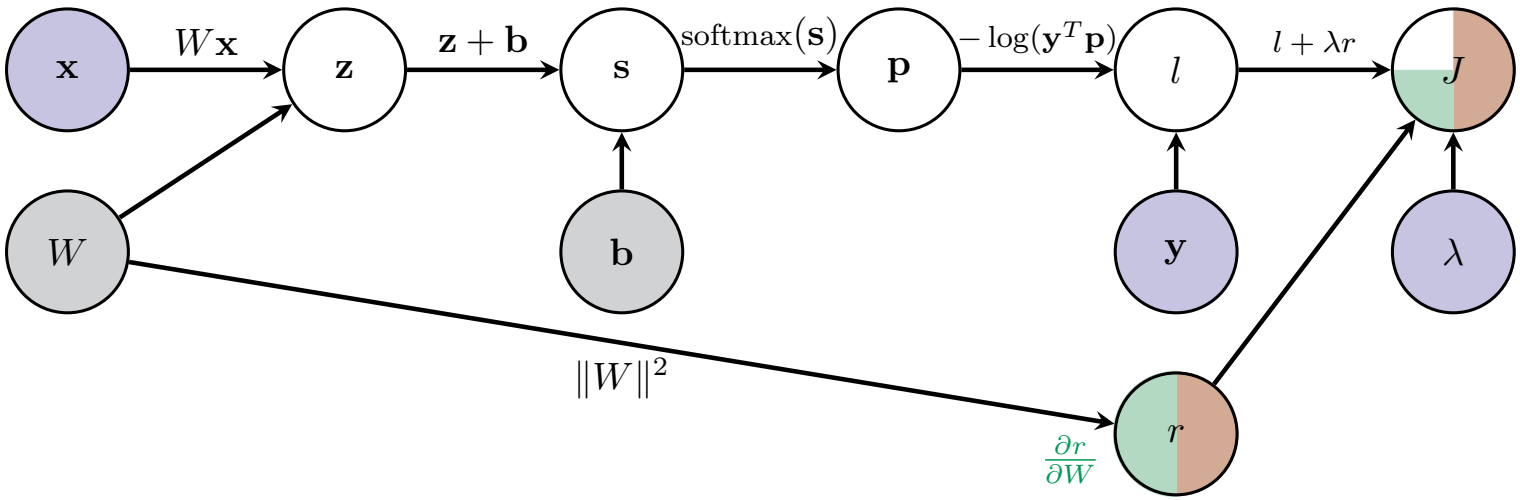


procedure PERFORMBACKPASS(G)
  J = GetResultNode(G) ▷ node with the value of cost function
  BackOp(J, G) ▷ Start the Backward-pass
end procedure

procedure BACKOP(**s**, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren(**s**, G)
  if $\mathcal{C}_\mathbf{s} = \emptyset$ **then** ▷ At the result node
    s.Grad = 1
  else
    if AllGradientsComputed($\mathcal{C}_\mathbf{s}$) **then** ▷ All $\frac{\partial J}{\partial \mathbf{c}}$ computed where $\mathbf{c} \in \mathcal{C}_\mathbf{s}$
      s.Grad = **0**
      for each $\mathbf{c} \in \mathcal{C}_\mathbf{s}$ **do**
        s.Grad += **c**.Grad * **c**.**s**.Jacobian ▷ $\frac{\partial J}{\partial \mathbf{s}} \mathrel{+}= \frac{\partial J}{\partial \mathbf{c}}\frac{\partial \mathbf{c}}{\partial \mathbf{s}}$
      end for
      s.GradComputed = true
    end if
  end if
  for each $\mathbf{p} \in \mathcal{P}_\mathbf{s}$ **do** ▷ Compute Jacobian of $f_\mathbf{s}$ w.r.t. each parent node
    s.**p**.Jacobian = $\frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}}$ ▷ $\frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}} = \frac{\partial \mathbf{s}}{\partial \mathbf{p}}$
    BackOp(**p**, G)
  end for
end procedure

Generic Backward Pass: Order of computations

Compute Jacobian of current node w.r.t. one parent

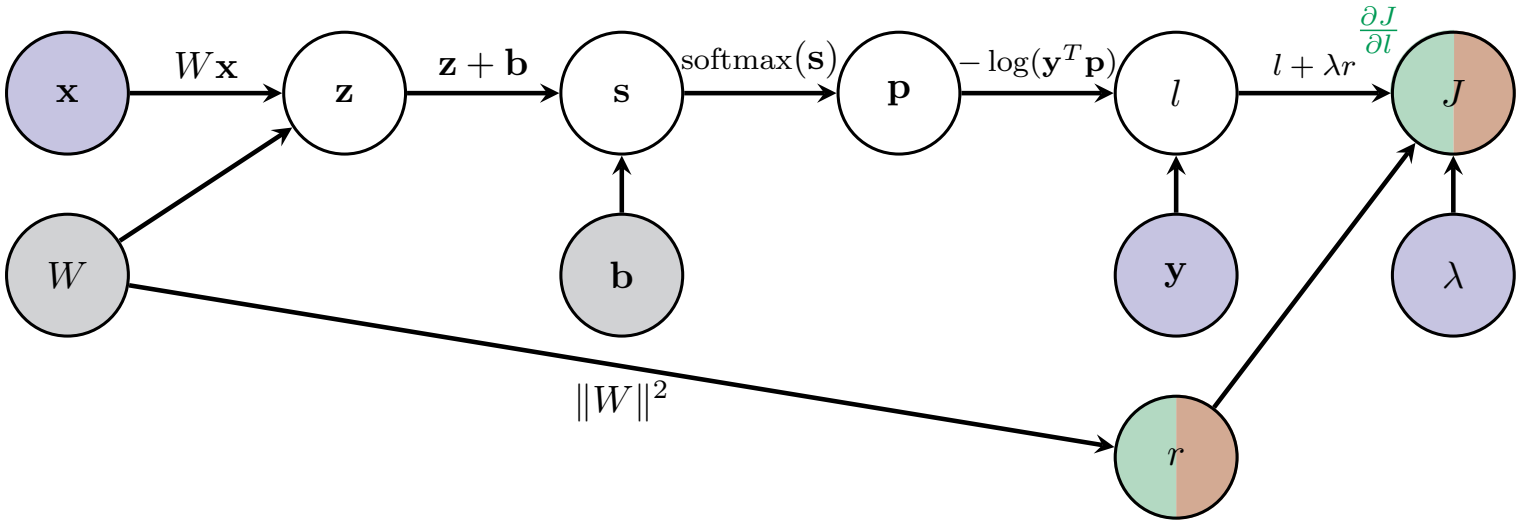


procedure PERFORMBACKPASS(G)
  J = GetResultNode(G) ▷ node with the value of cost function
  BackOp(J, G) ▷ Start the Backward-pass
end procedure

procedure BACKOP($\mathbf{s}$, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren($\mathbf{s}$, G)
  if $\mathcal{C}_\mathbf{s} = \emptyset$ **then** ▷ At the result node
    $\mathbf{s}$.Grad = 1
  else
    if AllGradientsComputed($\mathcal{C}_\mathbf{s}$) **then** ▷ All $\frac{\partial J}{\partial \mathbf{c}}$ computed where $\mathbf{c} \in \mathcal{C}_\mathbf{s}$
      $\mathbf{s}$.Grad = $\mathbf{0}$
      for each $\mathbf{c} \in \mathcal{C}_\mathbf{s}$ **do**
        $\mathbf{s}$.Grad += $\mathbf{c}$.Grad * $\mathbf{c}$.$\mathbf{s}$.Jacobian ▷ $\frac{\partial J}{\partial \mathbf{s}} \mathrel{+}= \frac{\partial J}{\partial \mathbf{c}} \frac{\partial \mathbf{c}}{\partial \mathbf{s}}$
      end for
      $\mathbf{s}$.GradComputed = true
    end if
  end if
  for each $\mathbf{p} \in \mathcal{P}_\mathbf{s}$ **do** ▷ Compute Jacobian of $f_\mathbf{s}$ w.r.t. each parent node
    $\mathbf{s}.\mathbf{p}.\text{Jacobian} = \frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}}$ ▷ $\frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}} = \frac{\partial \mathbf{s}}{\partial \mathbf{p}}$
    BackOp($\mathbf{p}$, G)
  end for
end procedure

Generic Backward Pass: Order of computations

Compute Jacobian of current node w.r.t. one parent

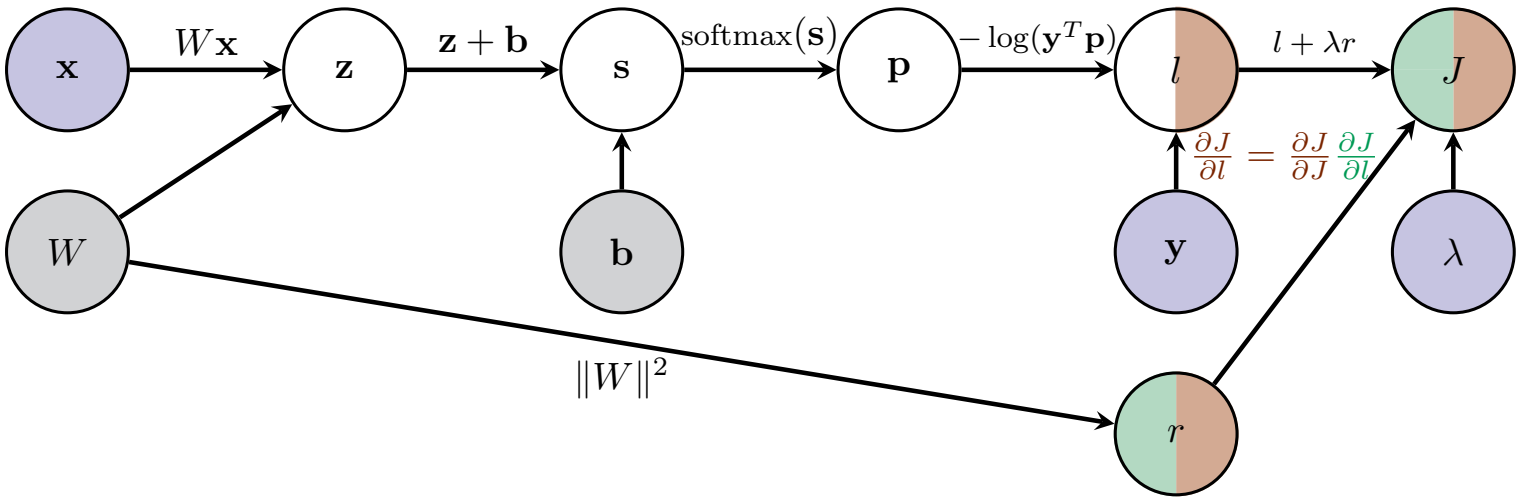


procedure PERFORMBACKPASS(G)
  J = GetResultNode(G) ▷ node with the value of cost function
  BackOp(J, G) ▷ Start the Backward-pass
end procedure

procedure BACKOP($\mathbf{s}$, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren($\mathbf{s}$, G)
  if $\mathcal{C}_\mathbf{s} = \emptyset$ **then** ▷ At the result node
    $\mathbf{s}$.Grad $= 1$
  else
    if AllGradientsComputed($\mathcal{C}_\mathbf{s}$) **then** ▷ All $\frac{\partial J}{\partial \mathbf{c}}$ computed where $\mathbf{c} \in \mathcal{C}_\mathbf{s}$
      $\mathbf{s}$.Grad $= \mathbf{0}$
      for each $\mathbf{c} \in \mathcal{C}_\mathbf{s}$ **do**
        $\mathbf{s}$.Grad += $\mathbf{c}$.Grad * $\mathbf{c}.\mathbf{s}$.Jacobian ▷ $\frac{\partial J}{\partial \mathbf{s}} \mathrel{+}= \frac{\partial J}{\partial \mathbf{c}} \frac{\partial \mathbf{c}}{\partial \mathbf{s}}$
      end for
      $\mathbf{s}$.GradComputed = true
    end if
  end if
  for each $\mathbf{p} \in \mathcal{P}_\mathbf{s}$ **do** ▷ Compute Jacobian of $f_\mathbf{s}$ w.r.t. each parent node
    $\mathbf{s}.\mathbf{p}.\text{Jacobian} = \frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}}$ ▷ $\frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}} = \frac{\partial \mathbf{s}}{\partial \mathbf{p}}$
    BackOp($\mathbf{p}$, G)
  end for
end procedure

Generic Backward Pass: Order of computations

Compute Gradient of current node

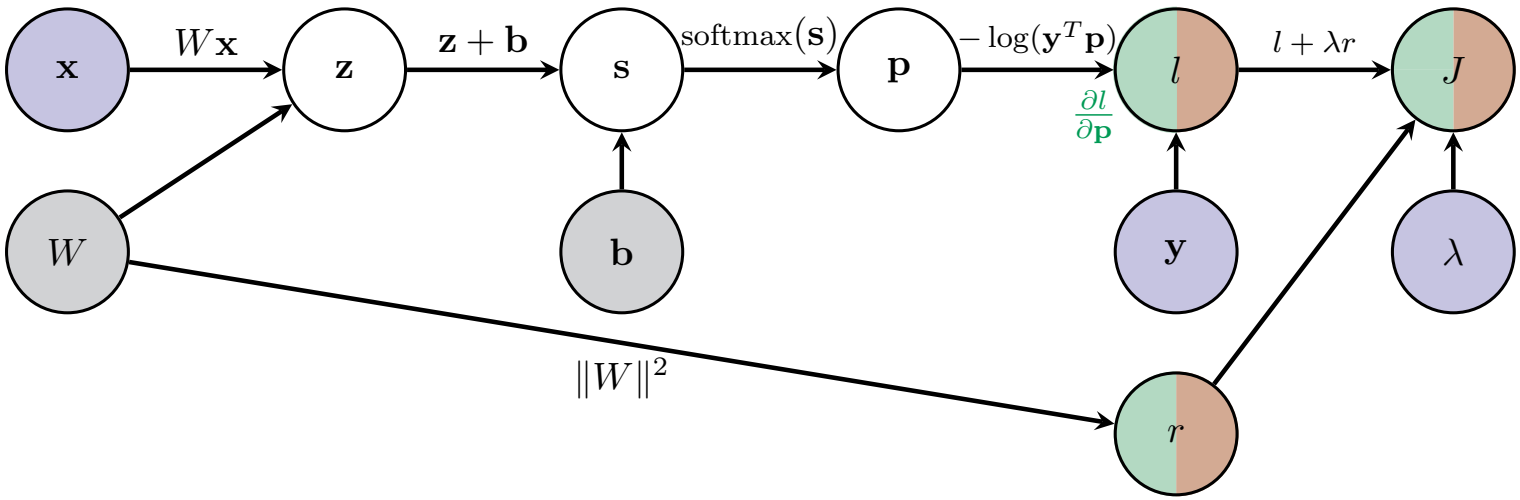


procedure PERFORMBACKPASS(G)
  J = GetResultNode(G) ▷ node with the value of cost function
  BackOp(J, G) ▷ Start the Backward-pass
end procedure

procedure BACKOP(**s**, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren(**s**, G)
  if $\mathcal{C}_\mathbf{s} = \emptyset$ **then** ▷ At the result node
    s.Grad = 1
  else
    if AllGradientsComputed($\mathcal{C}_\mathbf{s}$) **then** ▷ All $\frac{\partial J}{\partial \mathbf{c}}$ computed where $\mathbf{c} \in \mathcal{C}_\mathbf{s}$
      s.Grad = **0**
      for each $\mathbf{c} \in \mathcal{C}_\mathbf{s}$ **do**
        s.Grad += **c**.Grad * **c**.**s**.Jacobian ▷ $\frac{\partial J}{\partial \mathbf{s}} \mathrel{+}= \frac{\partial J}{\partial \mathbf{c}}\frac{\partial \mathbf{c}}{\partial \mathbf{s}}$
      end for
      s.GradComputed = true
    end if
  end if
  for each $\mathbf{p} \in \mathcal{P}_\mathbf{s}$ **do** ▷ Compute Jacobian of $f_\mathbf{s}$ w.r.t. each parent node
    s.**p**.Jacobian = $\frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}}$ ▷ $\frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}} = \frac{\partial \mathbf{s}}{\partial \mathbf{p}}$
    BackOp(**p**, G)
  end for
end procedure

Generic Backward Pass: Order of computations

Compute Jacobian of current node w.r.t. one parent

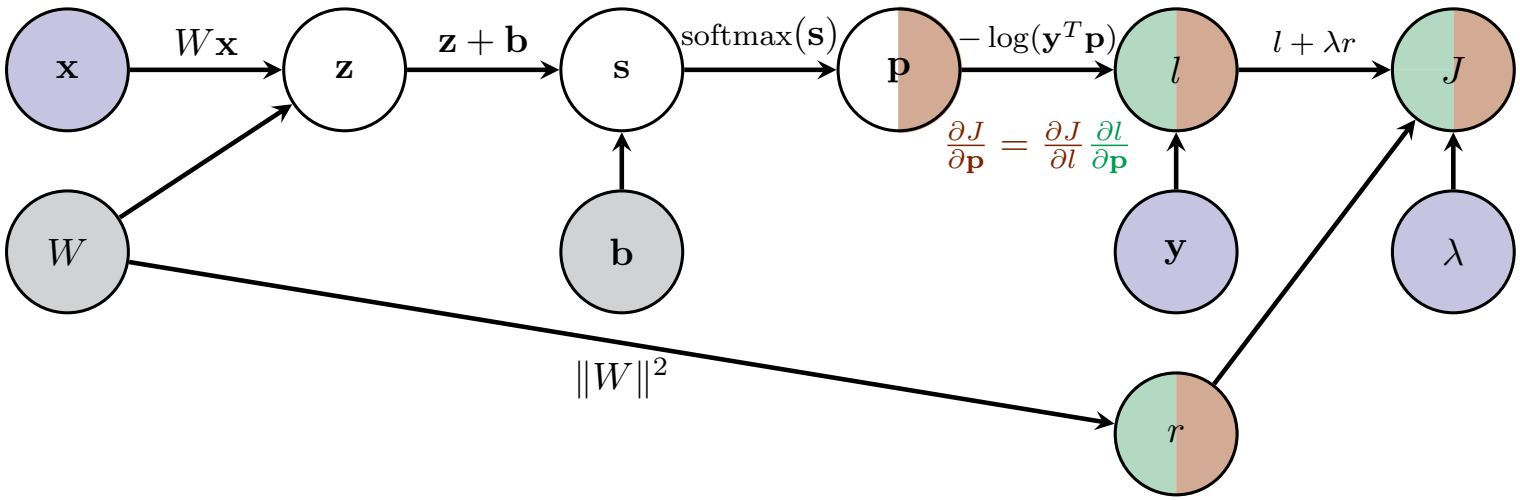


procedure PERFORMBACKPASS(G)
  J = GetResultNode(G) ▷ node with the value of cost function
  BackOp(J, G) ▷ Start the Backward-pass
end procedure

procedure BACKOP($\mathbf{s}$, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren($\mathbf{s}$, G)
  if $\mathcal{C}_\mathbf{s} = \emptyset$ **then** ▷ At the result node
    $\mathbf{s}$.Grad = 1
  else
    if AllGradientsComputed($\mathcal{C}_\mathbf{s}$) **then** ▷ All $\frac{\partial J}{\partial \mathbf{c}}$ computed where $\mathbf{c} \in \mathcal{C}_\mathbf{s}$
      $\mathbf{s}$.Grad = $\mathbf{0}$
      for each $\mathbf{c} \in \mathcal{C}_\mathbf{s}$ **do**
        $\mathbf{s}$.Grad += $\mathbf{c}$.Grad * $\mathbf{c}$.$\mathbf{s}$.Jacobian ▷ $\frac{\partial J}{\partial \mathbf{s}} \mathrel{+}= \frac{\partial J}{\partial \mathbf{c}} \frac{\partial \mathbf{c}}{\partial \mathbf{s}}$
      end for
      $\mathbf{s}$.GradComputed = true
    end if
  end if
  for each $\mathbf{p} \in \mathcal{P}_\mathbf{s}$ **do** ▷ Compute Jacobian of $f_\mathbf{s}$ w.r.t. each parent node
    $\mathbf{s}.\mathbf{p}.\text{Jacobian} = \frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}}$ ▷ $\frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}} = \frac{\partial \mathbf{s}}{\partial \mathbf{p}}$
    BackOp($\mathbf{p}$, G)
  end for
end procedure

Generic Backward Pass: Order of computations

Compute Gradient of current node

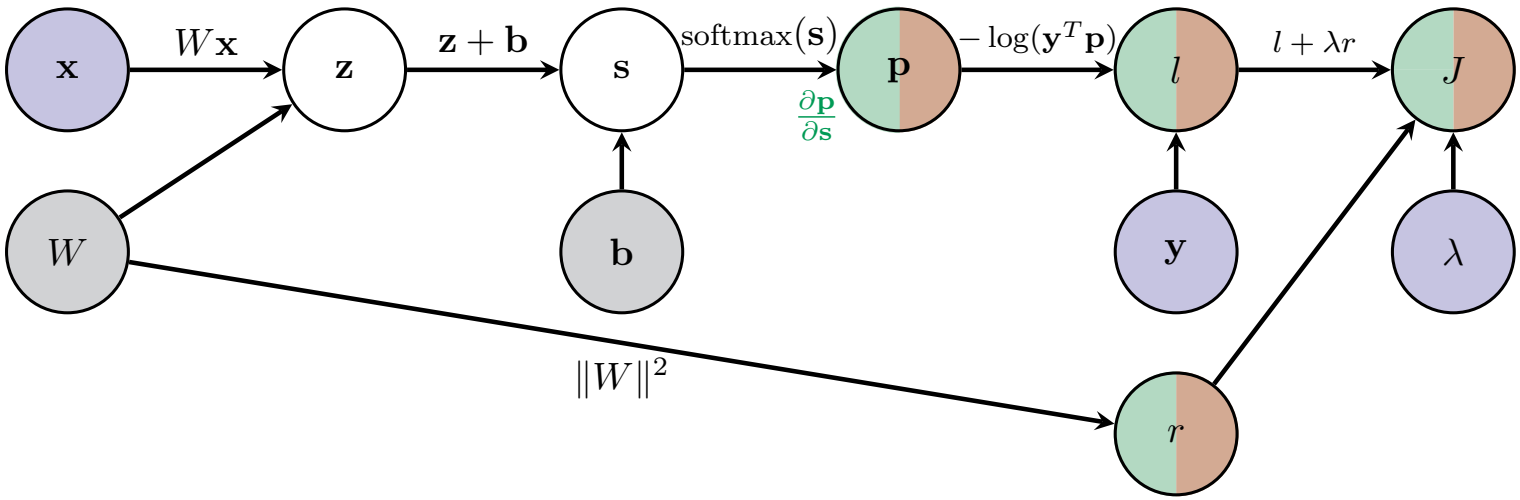


procedure PERFORMBACKPASS(G)
  J = GetResultNode(G) ▷ node with the value of cost function
  BackOp(J, G) ▷ Start the Backward-pass
end procedure

procedure BACKOP(**s**, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren(**s**, G)
  if $\mathcal{C}_\mathbf{s} = \emptyset$ **then** ▷ At the result node
    s.Grad = 1
  else
    if AllGradientsComputed($\mathcal{C}_\mathbf{s}$) **then** ▷ All $\frac{\partial J}{\partial \mathbf{c}}$ computed where $\mathbf{c} \in \mathcal{C}_\mathbf{s}$
      s.Grad = **0**
      for each $\mathbf{c} \in \mathcal{C}_\mathbf{s}$ **do**
        s.Grad += **c**.Grad * **c**.**s**.Jacobian ▷ $\frac{\partial J}{\partial \mathbf{s}} \mathrel{+}= \frac{\partial J}{\partial \mathbf{c}}\frac{\partial \mathbf{c}}{\partial \mathbf{s}}$
      end for
      s.GradComputed = true
    end if
  end if
  for each $\mathbf{p} \in \mathcal{P}_\mathbf{s}$ **do** ▷ Compute Jacobian of $f_\mathbf{s}$ w.r.t. each parent node
    s.**p**.Jacobian = $\frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}}$ ▷ $\frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}} = \frac{\partial \mathbf{s}}{\partial \mathbf{p}}$
    BackOp(**p**, G)
  end for
end procedure

Generic Backward Pass: Order of computations

Compute Jacobian of current node w.r.t. one parent

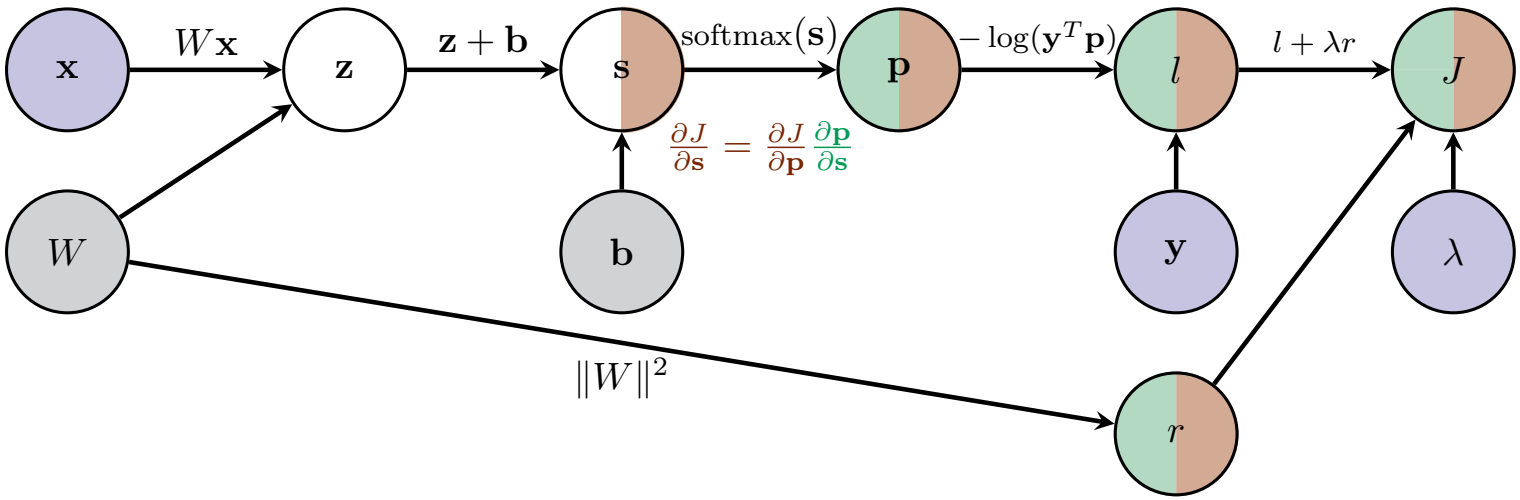


procedure PERFORMBACKPASS(G)
  J = GetResultNode(G) ▷ node with the value of cost function
  BackOp(J, G) ▷ Start the Backward-pass
end procedure

procedure BACKOP($\mathbf{s}$, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren($\mathbf{s}$, G)
  if $\mathcal{C}_\mathbf{s} = \emptyset$ **then** ▷ At the result node
    $\mathbf{s}$.Grad = 1
  else
    if AllGradientsComputed($\mathcal{C}_\mathbf{s}$) **then** ▷ All $\frac{\partial J}{\partial \mathbf{c}}$ computed where $\mathbf{c} \in \mathcal{C}_\mathbf{s}$
      $\mathbf{s}$.Grad = $\mathbf{0}$
      for each $\mathbf{c} \in \mathcal{C}_\mathbf{s}$ **do**
        $\mathbf{s}$.Grad += $\mathbf{c}$.Grad * $\mathbf{c}$.$\mathbf{s}$.Jacobian ▷ $\frac{\partial J}{\partial \mathbf{s}} \mathrel{+}= \frac{\partial J}{\partial \mathbf{c}} \frac{\partial \mathbf{c}}{\partial \mathbf{s}}$
      end for
      $\mathbf{s}$.GradComputed = true
    end if
  end if
  for each $\mathbf{p} \in \mathcal{P}_\mathbf{s}$ **do** ▷ Compute Jacobian of $f_\mathbf{s}$ w.r.t. each parent node
    $\mathbf{s}.\mathbf{p}.\text{Jacobian} = \frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}}$ ▷ $\frac{\partial f_\mathbf{s}(\mathcal{P}_\mathbf{s})}{\partial \mathbf{p}} = \frac{\partial \mathbf{s}}{\partial \mathbf{p}}$
    BackOp($\mathbf{p}$, G)
  end for
end procedure

Generic Backward Pass: Order of computations

Compute Gradient of current node



procedure PERFORMBACKPASS(G)
  J = GetResultNode(G) ▷ node with the value of cost function
  BackOp(J, G) ▷ Start the Backward-pass
end procedure

procedure BACKOP(**s**, G)
  $\mathcal{C}_\mathbf{s}$ = GetChildren(**s**, G)
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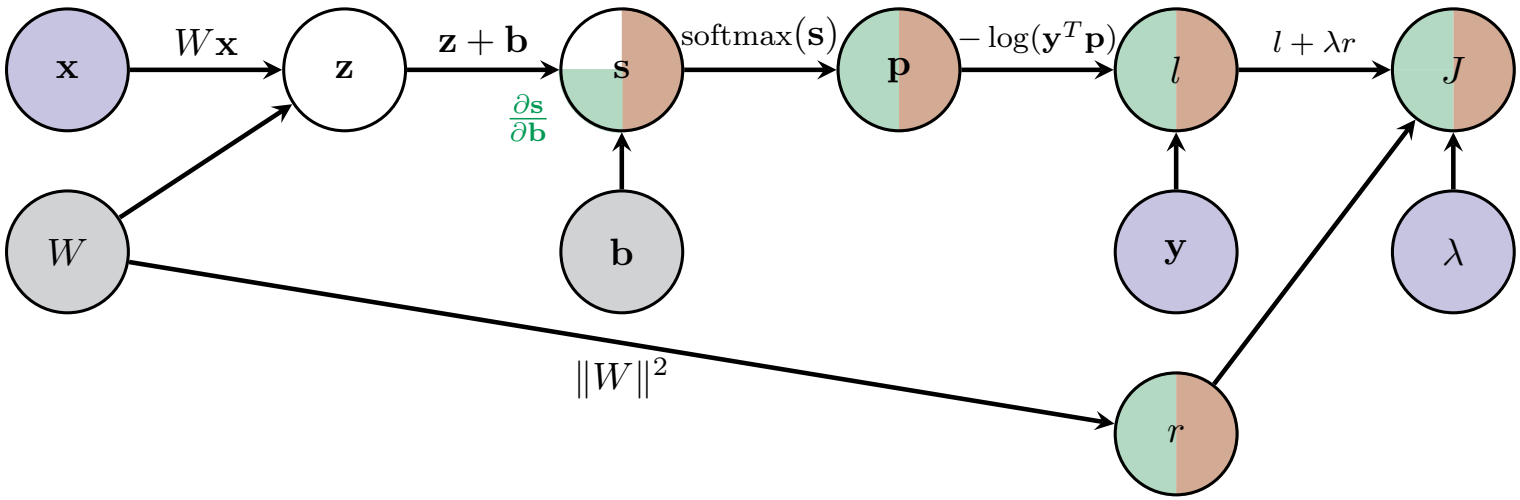
    BackOp(**p**, G)
  end for
end procedure

Generic Backward Pass: Order of computations

Compute Jacobian of current node w.r.t. one parent



procedure PERFORMBACKPASS(G)
  J = GetResultNode(G) ▷ node with the value of cost function
  BackOp(J, G) ▷ Start the Backward-pass
end procedure

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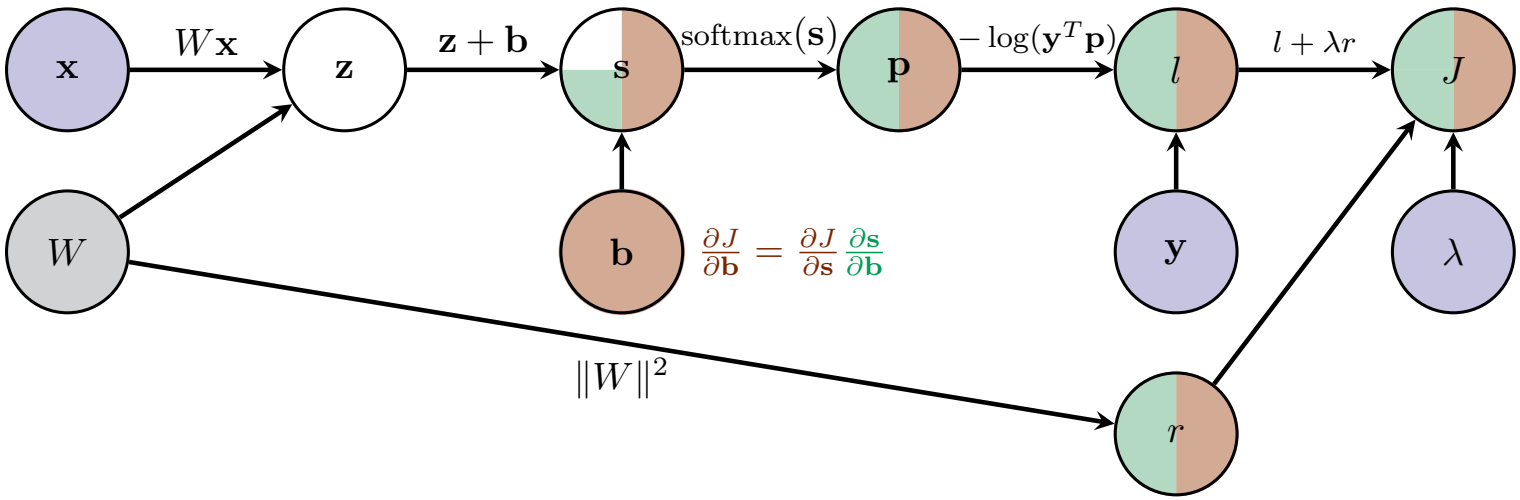
    BackOp($\mathbf{p}$, G)
  end for
end procedure

Generic Backward Pass: Order of computations

Compute Gradient of current node



procedure PERFORMBACKPASS(G)
  J = GetResultNode(G) ▷ node with the value of cost function
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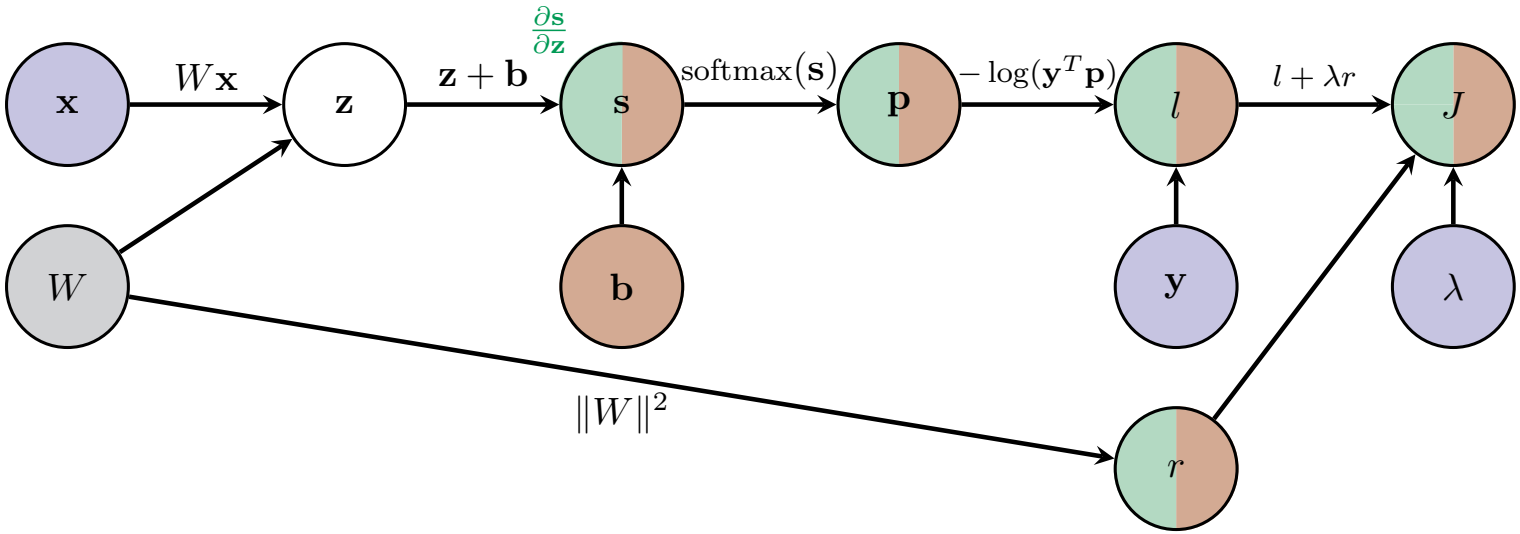
    BackOp(**p**, G)
  end for
end procedure

Generic Backward Pass: Order of computations

Compute Jacobian of current node w.r.t. one parent



procedure PERFORMBACKPASS(G)
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      s.Grad = **0**
      for each $\mathbf{c} \in \mathcal{C}_\mathbf{s}$ **do**
        s.Grad += c.Grad * c.s.Jacobian ▷ $\frac{\partial J}{\partial \mathbf{s}}$ += $\frac{\partial J}{\partial \mathbf{c}} \frac{\partial \mathbf{c}}{\partial \mathbf{s}}$
      end for
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    end if
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  for each $\mathbf{p} \in \mathcal{P}_\mathbf{s}$ **do** ▷ Compute Jacobian of $f_\mathbf{s}$ w.r.t. each parent node
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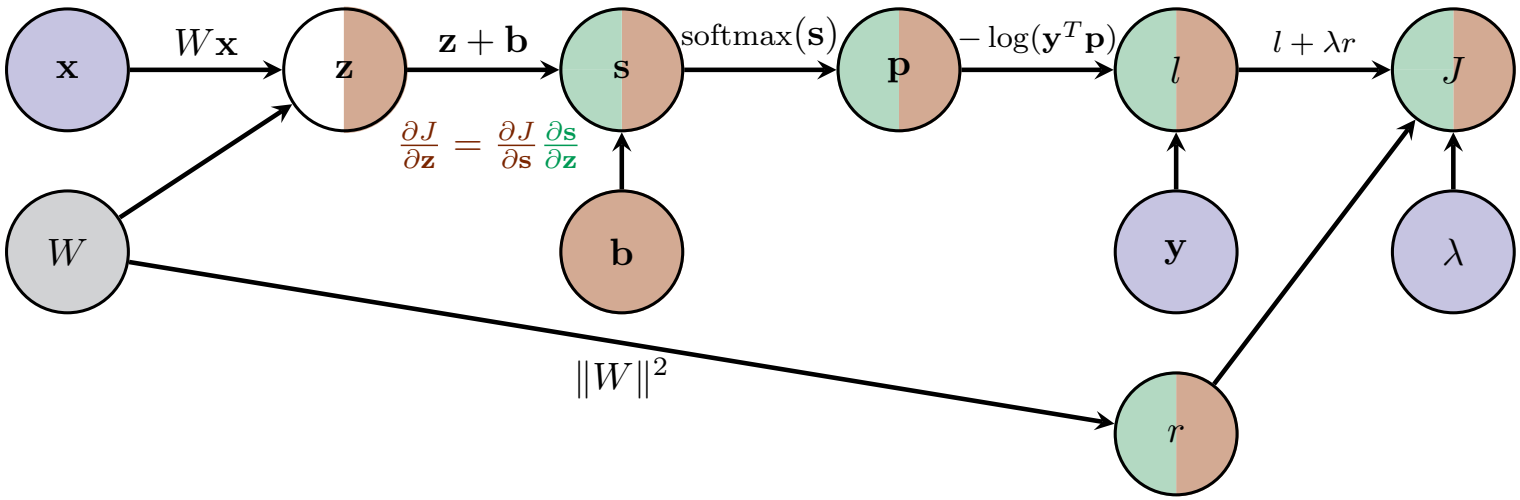
    BackOp(p, G)
  end for
end procedure

Generic Backward Pass: Order of computations

Compute Gradient of current node



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    BackOp(**p**, G)
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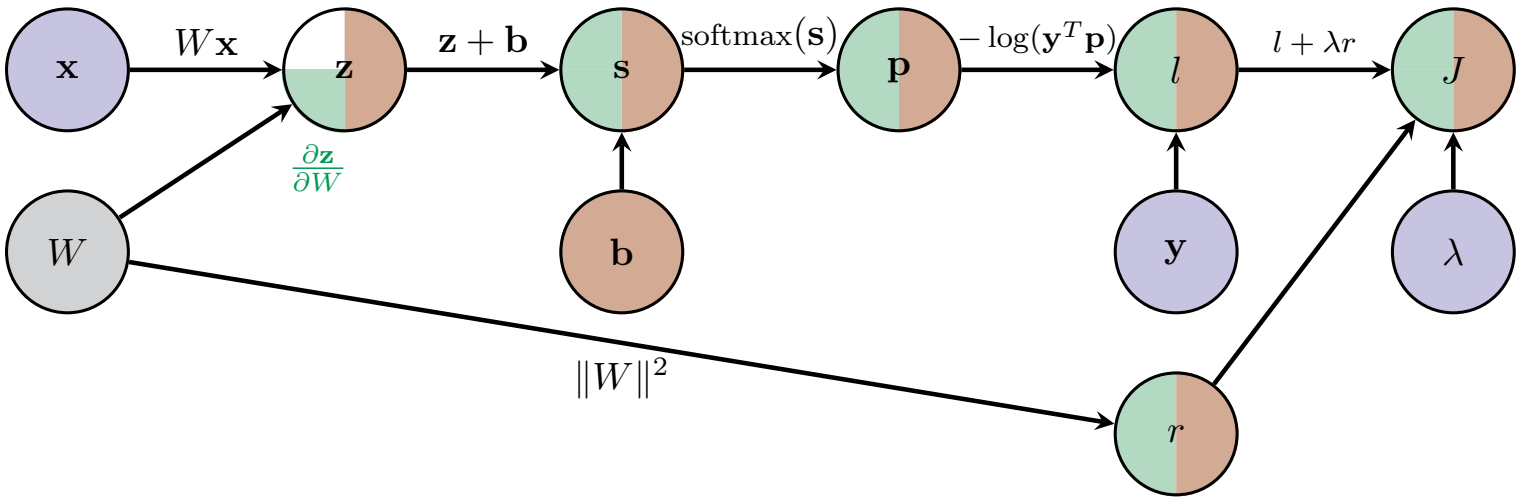
Generic Backward Pass: Order of computations

Compute Jacobian of current node w.r.t. one parent



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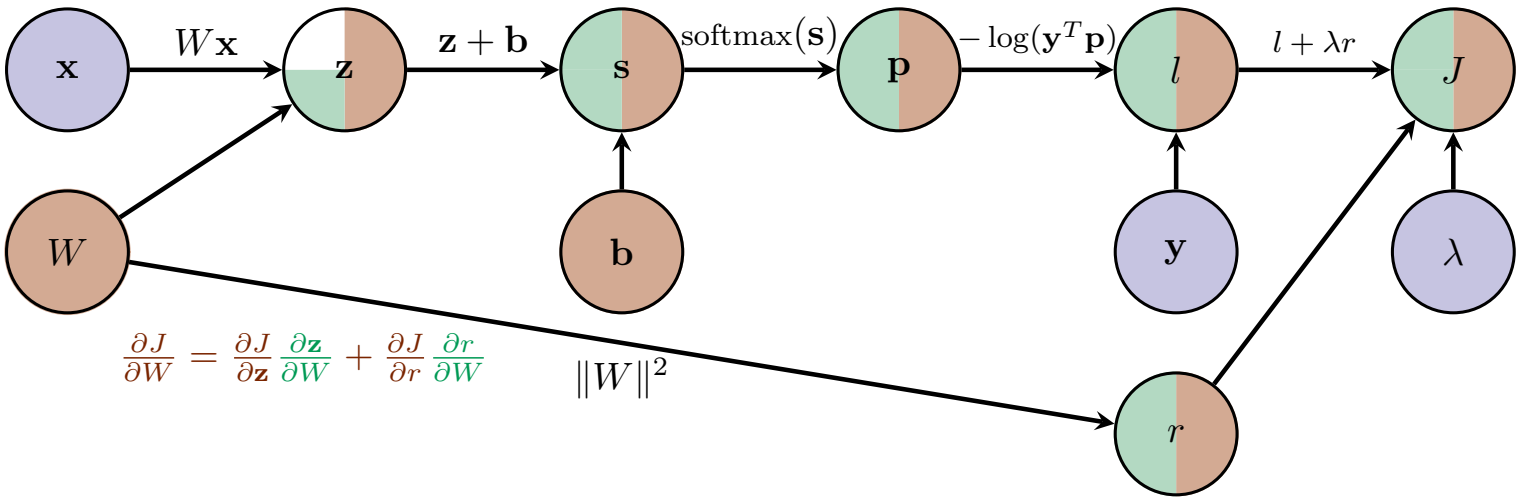
    BackOp(**p**, G)
  end for
end procedure

Generic Backward Pass: Order of computations

Compute Gradient of current node



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    BackOp(**p**, G)
  end for
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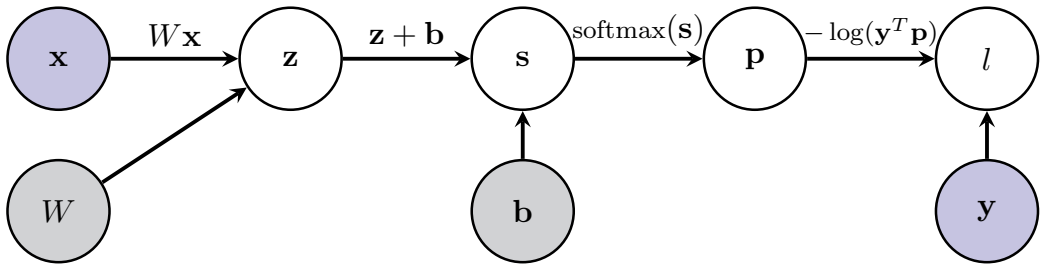
Issues we need to sort out



- Back-propagation when the computational graph is **not a chain**. ✓
- Derivative computations when the inputs and outputs are not scalars. ✓